

Digraph Fourier Transform via Spectral Dispersion Minimization

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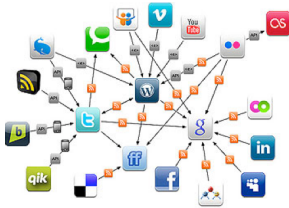
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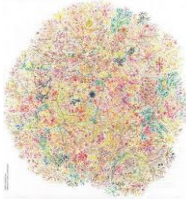
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Calgary, AB, April 20, 2018

Online social media



Internet



Clean energy and grid analytics



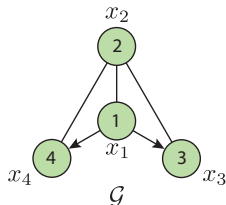
- ▶ **Network as graph** $\mathcal{G} = (\mathcal{V}, \mathcal{E})$: encode pairwise relationships
- ▶ **Desiderata**: Process, analyze and learn from **network data** [Kolaczyk'09]
- ▶ Interest here not in \mathcal{G} itself, but in **data** associated with **nodes** in \mathcal{V}
 - ⇒ The object of study is a **graph signal**
 - ⇒ **Ex**: Opinion profile, buffer levels, neural activity, epidemic

- ▶ Directed graph (digraph) \mathcal{G} with adjacency matrix \mathbf{A}

$\Rightarrow A_{ij}$ = Edge weight from node i to node j

- ▶ Define a signal $\mathbf{x} \in \mathbb{R}^N$ on top of the graph

$\Rightarrow x_i$ = Signal value at node i



- ▶ Associated with \mathcal{G} is the underlying undirected \mathcal{G}^u

\Rightarrow Laplacian matrix $\mathbf{L} = \mathbf{D} - \mathbf{A}^u$, eigenvectors $\mathbf{V} = [\mathbf{v}_1, \dots, \mathbf{v}_N]$

- ▶ Graph Signal Processing (GSP): exploit structure in \mathbf{A} or \mathbf{L} to process \mathbf{x}

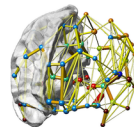
- ▶ Graph Fourier Transform (GFT): $\tilde{\mathbf{x}} = \mathbf{V}^T \mathbf{x}$ for undirected graphs

\Rightarrow Decompose \mathbf{x} into different modes of variation

\Rightarrow Inverse (i)GFT $\mathbf{x} = \mathbf{V}\tilde{\mathbf{x}}$, eigenvectors as frequency atoms

- ▶ Spectral analysis and filter design [Tremblay et al'17], [Isufi et al'16]

- ▶ Promising tool in **neuroscience** [Huang et al'16]
⇒ Graph frequency analyses of fMRI signals



- ▶ Noteworthy GFT approaches
 - ▶ Eigenvectors of the **Laplacian L** [Shuman et al'13]
 - ▶ Jordan decomposition of **A** [Sandryhaila-Moura'14], [Deri-Moura'17]
 - ▶ **Lovaśz extension** of the graph cut size [Sardellitti et al'17]
 - ▶ **Greedy** basis selection for spread modes [Shafipour et al'17]
 - ▶ **Generalized** variation operators and inner products [Girault et al'18]
- ▶ **Our contribution:** design a novel **digraph (D)GFT** such that
 - ▶ Bases offer notions of **frequency** and signal variation
 - ▶ Frequencies are (approximately) **equidistributed** in $[0, f_{\max}]$
 - ▶ Bases are **orthonormal**, so Parseval's identity holds

- ▶ **Total variation** of signal \mathbf{x} with respect to \mathbf{L}

$$\text{TV}(\mathbf{x}) = \mathbf{x}^T \mathbf{L} \mathbf{x} = \sum_{i,j=1, j>i}^N A_{ij}^u (x_i - x_j)^2$$

⇒ Smoothness measure on the graph \mathcal{G}^u

- ▶ For Laplacian eigenvectors $\mathbf{V} = [\mathbf{v}_1, \dots, \mathbf{v}_N] \Rightarrow \text{TV}(\mathbf{v}_k) = \lambda_k$
⇒ $0 = \lambda_1 < \dots \leq \lambda_N$ can be viewed as frequencies

- ▶ **Def: Directed variation** for signals over digraphs ($[x]_+ = \max(0, x)$)

$$\text{DV}(\mathbf{x}) := \sum_{i,j=1}^N A_{ij} [x_i - x_j]_+^2$$

⇒ Captures signal variation (flow) along directed edges
⇒ **Consistent**, since $\text{DV}(\mathbf{x}) \equiv \text{TV}(\mathbf{x})$ for undirected graphs

- ▶ **Goal:** find N **orthonormal** bases capturing different modes of DV on \mathcal{G}
- ▶ Collect the desired bases in a matrix $\mathbf{U} = [\mathbf{u}_1, \dots, \mathbf{u}_N] \in \mathbb{R}^{N \times N}$
 $\Rightarrow \mathbf{u}_k$ represents the k th frequency mode with $f_k := \text{DV}(\mathbf{u}_k)$
- ▶ Similar to the DFT, seek N **equidistributed** graph frequencies

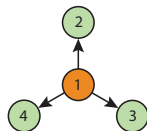
$$f_k = \text{DV}(\mathbf{u}_k) = \frac{k-1}{N-1} f_{\max}, \quad k = 1, \dots, N$$

$\Rightarrow f_{\max}$ is the maximum DV of a unit-norm graph signal on \mathcal{G}

- ▶ **Q:** Why spread frequencies?
 - ▶ Parsimonious representations of slowly-varying signals
 - ▶ Interpretability \Rightarrow better capture **low**, **medium**, and **high** frequencies
 - ▶ Aid filter design in the graph spectral domain

Ex: Directed variation minimization [Sardellitti et al'17]

$$\begin{aligned} \min_{\mathbf{U}} \quad & \sum_{i,j=1}^N A_{ij} [\mathbf{u}_i - \mathbf{u}_j]_+ \\ \text{s.t.} \quad & \mathbf{U}^T \mathbf{U} = \mathbf{I} \end{aligned}$$



$$\mathbf{U}^* = \begin{bmatrix} 0.5 & c & c & c \\ 0.5 & a & 0 & b \\ 0.5 & b & a & 0 \\ 0.5 & 0 & b & a \end{bmatrix}$$

- ▶ \mathbf{U}^* is the optimum basis where $a = \frac{1+\sqrt{5}}{4}$, $b = \frac{1-\sqrt{5}}{4}$, and $c = -0.5$
- ▶ All columns of \mathbf{U}^* satisfy $DV(\mathbf{u}_k^*) = 0$, $k = 1, \dots, 4$
 \Rightarrow Expansion $\mathbf{x} = \mathbf{U}^* \tilde{\mathbf{x}}$ fails to capture *different* modes of variation
- ▶ **Q:** Can we always find *equidistributed* frequencies in $[0, f_{\max}]$?

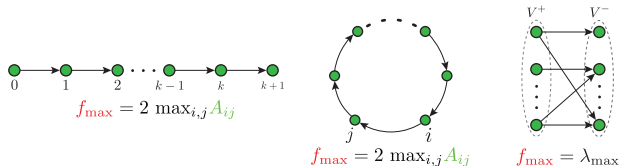
- ▶ Finding f_{\max} is in general challenging

$$\mathbf{u}_{\max} = \operatorname{argmax}_{\|\mathbf{u}\|=1} DV(\mathbf{u}) \quad \text{and} \quad f_{\max} := DV(\mathbf{u}_{\max}).$$

- ▶ Let \mathbf{v}_N be the dominant eigenvector of \mathbf{L}

$$\Rightarrow \text{Can 1/2-approximate } f_{\max} \text{ with } \tilde{\mathbf{u}}_{\max} = \operatorname{argmax}_{\mathbf{v} \in \{\mathbf{v}_N, -\mathbf{v}_N\}} DV(\mathbf{v})$$

- ▶ f_{\max} can be obtained analytically for particular classes though



- ▶ *Equidistributed* $f_k = \frac{k-1}{N-1} f_{\max}$ may **not** be feasible. **Ex:** In undirected \mathcal{G}^u

$$f_{\max}^u = \lambda_{\max} \quad \text{and} \quad \sum_{k=1}^N f_k = \sum_{k=1}^N \text{TV}(\mathbf{v}_k) = \text{trace}(\mathbf{L})$$

- ▶ **Idea:** Set $\mathbf{u}_1 = \mathbf{u}_{\min} := \frac{1}{\sqrt{N}} \mathbf{1}_N$ and $\mathbf{u}_N = \mathbf{u}_{\max}$ and minimize

$$\delta(\mathbf{U}) := \sum_{i=1}^{N-1} [\text{DV}(\mathbf{u}_{i+1}) - \text{DV}(\mathbf{u}_i)]^2$$

⇒ $\delta(\mathbf{U})$ is the *spectral dispersion function*

⇒ Minimized when the *free DV* values form an arithmetic sequence

- ▶ We cast the optimization problem of finding spread frequencies as

$$\min_{\mathbf{U}} \sum_{i=1}^{N-1} [DV(\mathbf{u}_{i+1}) - DV(\mathbf{u}_i)]^2$$

$$\text{subject to } \mathbf{U}^T \mathbf{U} = \mathbf{I}$$

$$\mathbf{u}_1 = \mathbf{u}_{\min}$$

$$\mathbf{u}_N = \mathbf{u}_{\max}$$

- ▶ Non-convex, **orthogonality-constrained** minimization of **smooth** $\delta(\mathbf{U})$
- ▶ Feasible since $\mathbf{u}_{\max} \perp \mathbf{u}_{\min}$
- ▶ Adopt a feasible method in the **Stiefel manifold** to design the **DFGT**:
 - Obtain f_{\max} (and \mathbf{u}_{\max}) by minimizing $-DV(\mathbf{u})$ over $\{\mathbf{u} \mid \mathbf{u}^T \mathbf{u} = 1\}$
 - Find the orthonormal basis \mathbf{U} with minimum spectral dispersion

- ▶ Rewrite the problem of finding orthonormal basis as

$$\begin{aligned} \min_{\mathbf{U}} \quad & \phi(\mathbf{U}) := \delta(\mathbf{U}) + \frac{\lambda}{2} (\|\mathbf{u}_1 - \mathbf{u}_{\min}\|^2 + \|\mathbf{u}_N - \mathbf{u}_{\max}\|^2) \\ \text{subject to} \quad & \mathbf{U}^T \mathbf{U} = \mathbf{I}_N \end{aligned}$$

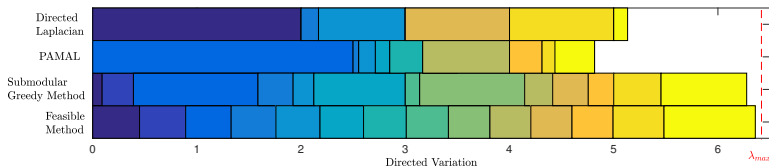
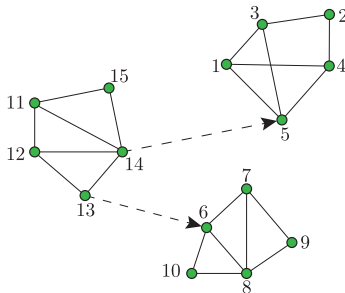
- ▶ Let \mathbf{U}_k be a feasible point at iteration k and the gradient $\mathbf{G}_k = \nabla \phi(\mathbf{U}_k)$
⇒ Skew-symmetric matrix $\mathbf{B}_k := \mathbf{G}_k \mathbf{U}_k^T - \mathbf{U}_k \mathbf{G}_k^T$
- ▶ Follow the update rule $\mathbf{U}_{k+1}(\tau) = (\mathbf{I} + \frac{\tau}{2} \mathbf{B}_k)^{-1} (\mathbf{I} - \frac{\tau}{2} \mathbf{B}_k) \mathbf{U}_k$
 - ▶ Cayley transform preserves orthogonality (i.e., $\mathbf{U}_{k+1}^T \mathbf{U}_{k+1} = \mathbf{I}$)
 - ▶ Is a descent path for a proper step size τ

Theorem (Wen et al'13) The procedure converges to a **stationary** point of smooth $\phi(\mathbf{U})$, while generating **feasible** points at every iteration.

- 1: **Input:** Adjacency matrix \mathbf{A} , parameters $\lambda > 0$ and $\epsilon > 0$
 - 2: Find \mathbf{u}_{\max} by a similar feasible method and set $\mathbf{u}_{\min} = \frac{1}{\sqrt{N}} \mathbf{1}_N$
 - 3: **Initialize** $k = 0$ and orthonormal $\mathbf{U}_0 \in \mathbb{R}^{N \times N}$ at random
 - 4: **repeat**
 - 5: Compute gradient $\mathbf{G}_k = \nabla \phi(\mathbf{U}_k) \in \mathbb{R}^{N \times N}$
 - 6: Form $\mathbf{B}_k = \mathbf{G}_k \mathbf{U}_k^T - \mathbf{U}_k \mathbf{G}_k^T$
 - 7: Select τ_k satisfying Armijo-Wolfe conditions
 - 8: Update $\mathbf{U}_{k+1}(\tau_k) = (\mathbf{I} + \frac{\tau_k}{2} \mathbf{B}_k)^{-1} (\mathbf{I} - \frac{\tau_k}{2} \mathbf{B}_k) \mathbf{U}_k$
 - 9: $k \leftarrow k + 1$
 - 10: **until** $\|\mathbf{U}_k - \mathbf{U}_{k-1}\|_F \leq \epsilon$
 - 11: **Return** $\hat{\mathbf{U}} = \mathbf{U}_k$
- Overall run-time is $\mathcal{O}(N^3)$ per iteration

Additional details in arXiv:1804.03000 [eess.SP]

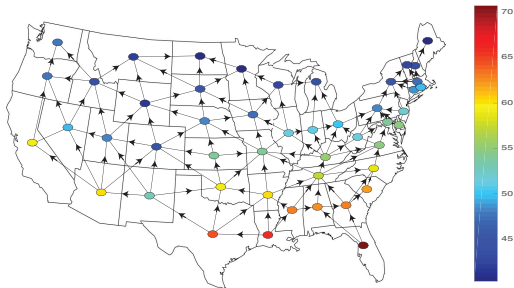
- ▶ Compute \mathbf{U} and directed variations using
 - ▶ **Directed Laplacian** eigenvectors [Chung'05]
 - ▶ **PAMAL** method [Sardellitti et al'17]
 - ▶ **Greedy** heuristic [Shafipour et al'17]
 - ▶ **Spectral dispersion minimization**



- ▶ Rescale DV values to $[0, 1]$ and calculate *spectral dispersion* $\delta(\mathbf{U})$
 - ⇒ **0.256**, **0.301**, **0.118**, and **0.076** respectively
 - ⇒ Confirms the proposed method yields a better frequency spread

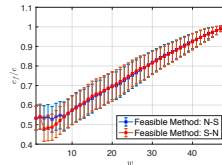
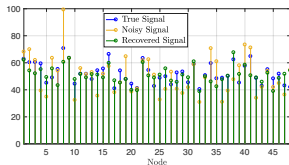
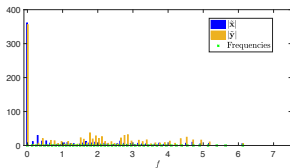
Numerical test: US average temperatures

- ▶ Consider the graph of the $N = 48$ **contiguous** United States
 - ⇒ Connect two states if they share a border
 - ⇒ Set arc directions from **lower** to **higher** latitudes



- ▶ Graph signal \mathbf{x} → Average annual *temperature* of each state

- ▶ Noisy signal $\mathbf{y} = \mathbf{x} + \mathbf{n}$, with $\mathbf{n} \sim \mathcal{N}(\mathbf{0}, 10 \times \mathbf{I}_M)$
- ▶ Define low-pass filter $\tilde{\mathbf{H}} = \text{diag}(\tilde{\mathbf{h}})$, where $\tilde{h}_i = \mathbb{I}\{i \leq 3\}$
- ▶ Recover signal via filtering $\hat{\mathbf{x}} = \mathbf{U}\tilde{\mathbf{H}}\tilde{\mathbf{y}} = \mathbf{U}\tilde{\mathbf{H}}\mathbf{U}^T \mathbf{y}$
 - \Rightarrow Compute recovery error $e_f = \frac{\|\hat{\mathbf{x}} - \mathbf{x}\|}{\|\mathbf{x}\|}$
 - \Rightarrow Reverse the edge orientations and repeat the experiment



- ▶ DGFT basis offers a parsimonious (i.e., bandlimited) signal representation
 - \Rightarrow Adequate network model improves the denoising performance

- ▶ Measure of **directed variation** to capture the notion of **frequency** on \mathcal{G}
- ▶ Find an **orthonormal** set of Fourier bases for signals on digraphs
 - ▶ Span a maximal frequency range $[0, f_{\max}]$
 - ▶ Frequency modes are as evenly distributed as possible
- ▶ Two-step **DGFT** basis design via a feasible method over Stiefel manifold
 - i) Find the maximum directed variation f_{\max} over the unit sphere
 - ii) Minimize a smooth **spectral dispersion** criterion over $[0, f_{\max}]$
 - ⇒ Provable convergence guarantees to a stationary point
- ▶ **Ongoing work and future directions**
 - ▶ Complexity of finding the maximum frequency f_{\max} on a digraph?
 - ⇒ If NP-hard, what is the best approximation ratio
 - ▶ Optimality gap between the local and global optimal dispersions?

Symposium on Graph Signal Processing

Topics of interest

- Graph-signal transforms and filters
- Distributed and non-linear graph SP
- Statistical graph SP
- Prediction and learning for graphs
- Network topology inference
- Recovery of sampled graph signals
- Control of network processes
- Signals in high-order and multiplex graphs
- Neural networks for graph data
- Topological data analysis
- Graph-based image and video processing
- Communications, sensor and power networks
- Neuroscience and other medical fields
- Web, economic and social networks

Paper submission due: **June 17, 2018**



Organizers:

- Gonzalo Mateos (Univ. of Rochester)
- Santiago Segarra (MIT)
- Sundeep Chepuri (TU Delft)