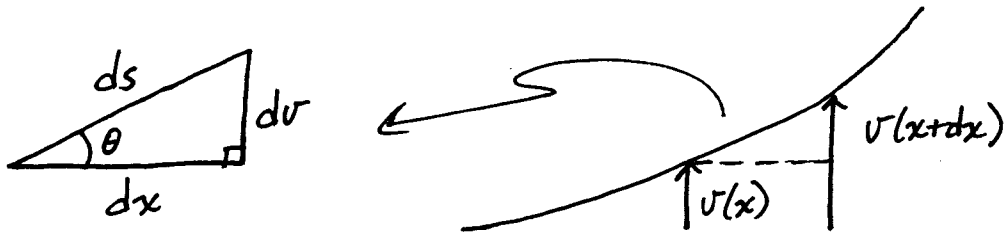
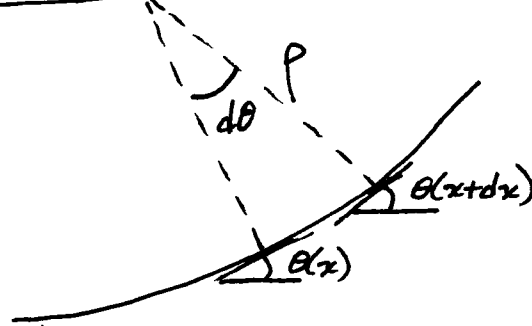


## Deflections of Beams



$$ds = \sqrt{dx^2 + dv^2} = dx \sqrt{1 + \left(\frac{dv}{dx}\right)^2} \approx dx \left[1 + \frac{1}{2} \left(\frac{dv}{dx}\right)^2\right]$$

So, for  $\frac{dv}{dx} \ll 1 \rightarrow ds \approx dx$

$$ds = \rho d\theta \rightarrow dx = \rho d\theta \rightarrow$$

$$\boxed{\frac{d\theta}{dx} = \frac{1}{\rho} = \chi}$$

$\tan \theta = \frac{dv}{dx}$ , but if  $\frac{dv}{dx} \ll 1$  then  $\tan \theta \approx \theta$

$$\rightarrow \boxed{\theta = \frac{dv}{dx} \text{ when } \frac{dv}{dx} \ll 1}$$

Finally, 
$$\boxed{\chi = \frac{d\theta}{dx} = \frac{d}{dx} \left( \frac{dv}{dx} \right) = \frac{d^2v}{dx^2}}$$

\* This is entirely an analysis of kinematics.

Next, recall that analyses of equilibrium and material law lead to:

$$M = EI \chi$$

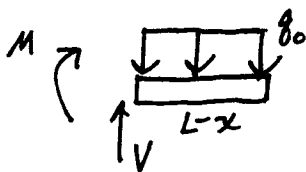
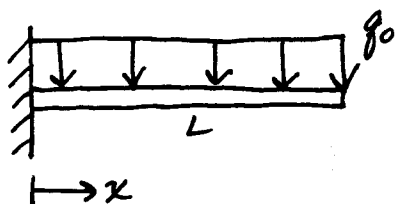
So,

$$\frac{M}{EI} = \frac{d^2 \chi}{dx^2} \quad ***$$

or with  $\frac{dM}{dx} = V \rightarrow \frac{V}{EI} = \frac{d^3 \chi}{dx^3}$

or with  $\frac{dV}{dx} = -q \rightarrow \frac{-q}{EI} = \frac{d^4 \chi}{dx^4}$

Example



$$\sum M_z^x = -M - q_0(L-x) \frac{L-x}{2} = 0$$

$$M(x) = -\frac{q_0}{2} (L-x)^2$$

$$\frac{d^2 \chi}{dx^2} = -\frac{q_0}{2EI} (L-x)^2$$

$$\rightarrow \frac{d\chi}{dx} = \frac{q_0}{6EI} (L-x)^3 + C_1 \quad \left. \frac{d\chi}{dx} \right|_{x=0} = 0 \rightarrow C_1 = -\frac{q_0 L^3}{6EI}$$

$$\rightarrow \chi = -\frac{q_0}{24EI} (L-x)^4 - \frac{q_0 L^3}{6EI} x + C_2, \quad \chi(0) = 0 \rightarrow C_2 = \frac{q_0 L^4}{24EI}$$

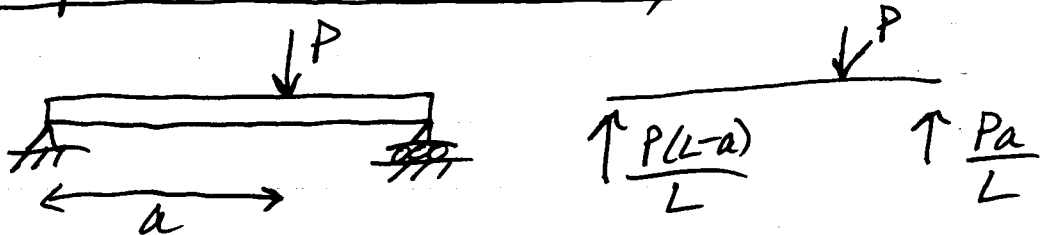
$$\rightarrow v(x) = \frac{-\beta_0}{24EI} [(L-x)^4 - 4L^3x + L^4]$$

$$\delta_{\max} = -v_{\max} = -v(x=L) = \frac{\beta_0 L^4}{8EI}$$

$$\theta_{\max} = -\theta(x=L) = \frac{\beta_0 L^3}{6EI}$$

Note that we could have started from  $f(x)$  and integrated 4 times, requiring us to find the 4 constants of integration.

Example with a discontinuity



$$0 \leq x < a : \quad \begin{aligned} q(x) &= 0 \\ q(x) &= -\frac{dV}{dx} \rightarrow V(x) = C_1 \\ V(x) &= \frac{dM}{dx} \rightarrow M(x) = C_1x + C_2 \\ M(x) &= EI \frac{d\theta}{dx} \rightarrow \theta(x) = \frac{1}{2}C_1x^2 + C_2x + C_3 \\ \theta(x) &= \frac{dv}{dx} \rightarrow EI v(x) = \frac{1}{6}C_1x^3 + \frac{1}{2}C_2x^2 \\ &\quad + C_3x + C_4 \end{aligned}$$

$$\text{Boundary conditions: } v(x=0) = \frac{P(L-a)}{L} \\ \therefore C_1 = \frac{P(L-a)}{L}$$

$$M(x=0) = 0 = C_1(0) + C_2 \rightarrow C_2 = 0$$

$$v(x=0) = 0 \rightarrow C_4 = 0$$

~~•~~ We do not know  $\theta(x=0)$ .

$$\begin{aligned}
 a < x \leq L : \quad & f(x) = 0 \\
 & \rightarrow V(x) = d_1 \\
 & M(x) = d_1 x + d_2 \\
 EI \theta(x) &= \frac{1}{2} d_1 x^2 + d_2 x + d_3 \\
 EI V(x) &= \frac{1}{6} d_1 x^3 + \frac{1}{2} d_2 x^2 + d_3 x + d_4
 \end{aligned}$$

$$\begin{aligned}
 \text{Boundary conditions: } \quad & V(L) = -\frac{Pa}{L} \rightarrow d_1 = -\frac{Pa}{L} \\
 & M(L) = 0 \rightarrow d_2 = Pa \\
 EI V(L) = 0 & \rightarrow -\frac{PaL^2}{6} + \frac{PaL^2}{2} + d_3 L + d_4 = 0
 \end{aligned}$$

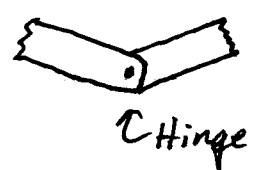
Again, we do not know  $\theta(L)$ . So, now we have  $d_3$ ,  $d_4$ , and  $c_3$  as unknowns, but only one equation for their solution. Now what? Well, we have continuity (or jump) conditions at  $x=a$ . We already know that,

$$\begin{aligned}
 & V(x=a^+) - V(x=a^-) = -P \\
 \text{and } & M(x=a^+) - M(x=a^-) = -M_0 = 0 \text{ in this case}
 \end{aligned}$$

$$\begin{aligned}
 \text{But these are already satisfied: } \quad & V(x=a^+) = -\frac{Pa}{L} \\
 & V(x=a^-) = \frac{P(L-a)}{L} \\
 & V^+ - V^- = -P \quad \checkmark \\
 & M(x=a^+) = -\frac{Pa}{L} \cdot a + Pa = Pa \left(1 - \frac{a}{L}\right) \\
 & M(x=a^-) = \frac{P(L-a)}{L} \cdot a = Pa \left(1 - \frac{a}{L}\right) \\
 & M^+ - M^- = 0 \quad \checkmark
 \end{aligned}$$

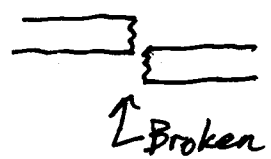
Now, we also need to match  $v(x)$  and  $\theta(x)$ .

If there is no hinge at  $x=a$ , then  $\theta(x=a^+) = \theta(x=a^-)$ .



If there is a hinge at  $x=a$ , then  $M(x=a^+) = M(x=a^-) = 0$ .

If the beam is not broken at  $x=a$ , then  $v(x=a^+) = v(x=a^-)$ .



If the beam is broken at  $x=a$ , then  $v(x=a^+) - v(x=a^-) = 0$ .

So, for our problem we have,  $\theta(x=a^+) = \theta(x=a^-)$  &  $v(x=a^+) = v(x=a^-)$ .

$$\theta : -\frac{1}{2} \frac{Pa}{L} a^2 + Pa \cdot a + d_3 = \frac{1}{2} \frac{P(L-a)}{L} a^2 + c_3$$

$$-\frac{1}{2} \frac{Pa^3}{L} + Pa^2 + d_3 = \frac{1}{2} Pa^2 - \frac{1}{2} \frac{Pa^3}{L} + c_3$$

$$v : -\frac{1}{6} \frac{Pa}{L} a^3 + \frac{1}{2} Pa \cdot a^2 + d_3 a + d_4 = \frac{1}{6} \frac{P(L-a)}{L} a^3 + c_3 a$$

$$= \frac{1}{6} Pa^3 - \frac{1}{6} \frac{Pa}{L} a^3 + c_3 a$$

$$\textcircled{1} d_3 - c_3 = -\frac{1}{2} Pa^2$$

$$a(d_3 - c_3) + d_4 = -\frac{1}{3} Pa^3$$

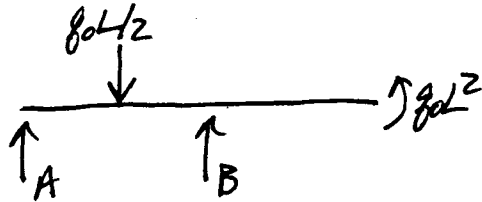
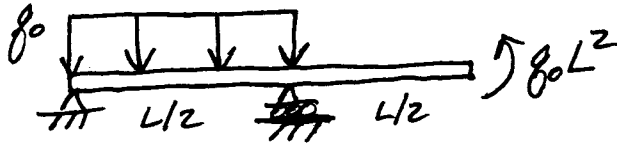
$$-\frac{1}{2} Pa^3 + d_4 = -\frac{1}{3} Pa^3 \rightarrow d_4 = \frac{1}{6} Pa^3$$

$$\text{From } v(L) = 0 \rightarrow \frac{PaL^2}{3} + d_3L + \frac{1}{6} Pa^3 = 0 \rightarrow d_3 = -\frac{PaL}{3} - \frac{Pa^3}{6L}$$

$$= -\frac{Pa^2}{3a} \left( \frac{L}{3a} + \frac{a}{6L} \right)$$

$$\text{then } \textcircled{1} \rightarrow c_3 = \frac{1}{2} Pa^2 \left( 1 - \frac{2L}{3a} - \frac{a}{3L} \right)$$

Example



$$\sum M_z^A = q_0 L^2 + \frac{BL}{2} - \frac{q_0 L^2}{8} = 0$$

$$B = -\frac{7}{4} q_0 L$$

$$\sum F_y = A + B - \frac{q_0 L}{2} = 0 \rightarrow A = \frac{9}{4} q_0 L$$

$0 \leq x < \frac{L}{2}$ :

$$q(x) = q_0$$

$$\rightarrow V(x) = -q_0 x + C_1$$

$$M(x) = -\frac{1}{2} q_0 x^2 + C_1 x + C_2$$

$$EI \theta(x) = -\frac{1}{6} q_0 x^3 + \frac{1}{2} C_1 x^2 + C_2 x + C_3$$

$$EI v(x) = -\frac{1}{24} q_0 x^4 + \frac{1}{6} C_1 x^3 + \frac{1}{2} C_2 x^2 + C_3 x + C_4$$

BCs:  $v(0) = 0 \rightarrow C_4 = 0$

$M(0) = 0 \rightarrow C_2 = 0$

$V(0) = A = \frac{9}{4} q_0 L \rightarrow C_1 = \frac{9}{4} q_0 L$

$v(\frac{L}{2}) = 0$

$$\rightarrow -\frac{1}{24} q_0 \left(\frac{L}{2}\right)^4 + \frac{1}{6} \frac{9}{4} q_0 L \left(\frac{L}{2}\right)^3 + C_3 \frac{L}{2} = 0$$

$$\rightarrow C_3 = -\frac{17}{192} q_0 L^3$$

$$\rightarrow EI v(x) = -\frac{1}{24} q_0 x^4 + \frac{9}{24} q_0 L x^3 - \frac{17}{192} q_0 L^3 x$$

$\frac{L}{2} < x \leq L$ :  $q(x) = 0 \rightarrow V(x) = d_1$

$$M(x) = d_1 x + d_2$$

$$EI \theta(x) = \frac{1}{2} d_1 x^2 + d_2 x + d_3$$

$$EI v(x) = \frac{1}{6} d_1 x^3 + \frac{1}{2} d_2 x^2 + d_3 x + d_4$$

BCs:  $V(x=L) = 0 \rightarrow d_1 = 0$   
 $M(x=L) = q_0 L^2 \rightarrow d_2 = q_0 L^2$  (b/c  $d_1 = 0$ )

Matching:  $\theta(x = \frac{L}{2}^-) = \theta(x = \frac{L}{2}^+)$   
 $-\frac{1}{6} q_0 (\frac{L}{2})^3 + \frac{q}{8} q_0 L (\frac{L}{2})^2 - \frac{17}{192} q_0 L^3 = q_0 L^2 (\frac{L}{2}) + d_3$

$$\rightarrow d_3 = -\frac{21}{64} q_0 L^3$$

$$V(x = \frac{L}{2}) = 0 = \frac{q_0 L^2}{2} (\frac{L}{2})^2 - \frac{21}{64} q_0 L^3 (\frac{L}{2}) + d_4$$

$$\rightarrow d_4 = \frac{5}{128} q_0 L^4$$

$$\rightarrow EI V(x) = \frac{1}{2} q_0 L^2 x^2 - \frac{21}{64} q_0 L^3 x + \frac{5}{128} q_0 L^4$$

Design specifications could include max/min axial stress, shear stress, and deflections.

Shear stress:  $\tau = \frac{VQ}{Ib}$  so we need  $V_{max}$ .

$V_{max}$  occurs where  $q(x) = 0$  or at external/internal boundaries.

$q(x) = 0$  for  $\frac{L}{2} \leq x \leq L$ , but  $V(x) = 0$  in this range.

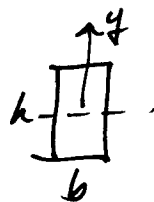
$q(x) \neq 0$  for  $0 \leq x < \frac{L}{2}$ , so  $x = 0$  and  $x = \frac{L}{2}$  are critical points.

$$V(x=0) = A = \frac{q}{4} q_0 L$$

$$V(x = \frac{L}{2}) = -q_0 \frac{L}{2} + \frac{q}{4} q_0 L = \frac{7}{4} q_0 L = -B \checkmark$$

so,  $V_{max} = \frac{9}{4} g_0 L$

Let's say the cross-section is



Then,  $\tau_{max}$  occurs at  $y=0$ ,  
 with  $b(y) = b$ ,  $Q(y) = \frac{bh^2}{8} - \frac{1}{2}by^2 \rightarrow Q(0) = \frac{bh^2}{8}$   
 and  $I = \frac{1}{12}bh^3$ .

\* 
$$\rightarrow \tau_{max} = \frac{9}{4} g_0 L \frac{bh^2/8}{\frac{1}{12}bh^3} = \frac{3}{2} \underbrace{\left( \frac{9}{4} g_0 L \right)}_{V_{max}/A} \frac{1}{bh}$$

You can remember  $\tau_{max} = \frac{3}{2} \frac{V}{A}$  for a rectangular section.

$$\sigma_{max/min} = \pm \frac{M y_{max/min}}{I} = \pm |M_{max}| \frac{h/2}{\frac{1}{12}bh^3}$$

$\frac{6}{bh^2}$

$|M_{max}|$  occurs where  $V(x) = 0$  or boundaries.

$V(x) = 0$  for  $\frac{L}{2} < x \leq L$  and  $M = g_0 L^2$

in  $0 \leq x < \frac{L}{2}$  :  $V(x) = -g_0 x + \frac{9}{4} g_0 L = 0$   
 $x = \frac{9}{4} L$  X Not in the range  $[0, \frac{L}{2})$

\*\*  $\therefore M_{max} = g_0 L^2 \rightarrow \sigma_{max/min} = \pm 6 g_0 L^2 / bh^2$  throughout  $(\frac{L}{2}, L]$   
 $\left( \frac{c}{2} \right)$



$v_{\max/\min}$  occurs where  $\theta = 0$  or boundaries

$$\text{for } \frac{L}{2} < x \leq L : EI\theta(x) = f_0 L^2 x - \frac{21}{64} f_0 L^3 = 0$$

$$\rightarrow x = \frac{21}{64} L \quad \text{Not in } \left(\frac{L}{2}, L\right]$$

\*\*\* So  $v_{\max}$  is at  $x = L$   $\rightarrow v(L) = \frac{27}{128} \frac{f_0 L^4}{EI}$

$$0 \leq x < \frac{L}{2} : EI\theta(x) = -\frac{1}{6} f_0 x^3 + \frac{9}{8} f_0 L x^2 - \frac{17}{192} f_0 L^3 = 0$$

Mathematica:  $x = 0.2867L$  is the only root in  $\left[0, \frac{L}{2}\right)$

\*\*\*  $\rightarrow v_{\min} = -0.0139 \frac{f_0 L^2}{EI}$

Note that  $|v_{\min}| < |v_{\max}|$  which should satisfy your intuition.