

**ME 364L/384Q.4: Automatic Control System Design**  
**Fall 2025, Unique No. 20275/20460**  
<https://utexas.instructure.com/courses/1430917>

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| <b>Instructor:</b>      | Prof. Raul G. Longoria                                                                                                   |
| <b>Contact info:</b>    | <a href="mailto:r.longoria@mail.utexas.edu">r.longoria@mail.utexas.edu</a>                                               |
| <b>Lectures:</b>        | MW 12:30-2:00p, ETC 4.150                                                                                                |
| <b>Office/hours:</b>    | TTH 1-2 pm and by appt (zoom)<br><a href="https://utexas.zoom.us/my/r.longoria">https://utexas.zoom.us/my/r.longoria</a> |
| <b>TA:</b>              | Seong-Hyo Ahn                                                                                                            |
| <b>TA Contact info:</b> | Use Canvas messaging or Ed Discussion                                                                                    |

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**1. Course objectives<sup>1</sup>:** This course introduces the modeling, analysis, and design of feedback-controlled systems. The role of feedback and its use in applications is described, with an emphasis on how feedback influences system response and stability. Linearization methods are reviewed to support the formulation of transfer functions and linear state-space equations. Routh, Nyquist, Bode, and root locus methods are introduced and applied, along with mathematical tools for time and frequency domain design and analysis. State-space control principles are also introduced, as they arise in many practical applications and in advanced control methods.

**2. Prerequisites:** ME 344 is a **required** prerequisite for undergraduates enrolled in this course. Graduate students are expected to have knowledge equivalent to that taught in ME 344. You are also expected to be familiar with Matlab or Python for analysis and simulation.

**3. Format and procedures:** This course is delivered through lecture-based presentations. Exercises and case studies will be completed in the form of homework assignments. Class discussion, in-class examples, and short quizzes will be used to encourage participation.

**4. ME 364L vs. 384Q:** Graduate students should register for ME 384Q (**especially students in the ME Integrated BS/MSE program**). As required by the graduate school, there are explicit differences in assignments, quizzes, and expectations for students enrolled in the undergraduate (364L) section versus the graduate (384Q) section.

**5. Course schedule:** This syllabus communicates current plans and objectives. Adjustments may be made based on how the class is progressing. *Always* refer to the *Home Page* on Canvas. The proposed schedule of topics is provided in Table 1 on the last page of this syllabus.

**6. Course Readings/Materials:** The course will primarily draw from: 1) Ogata, Modern Control Engineering, Prentice-Hall (3rd ed or later) and 2) Franklin, Powell, and Emami-Naeini, Feedback Control of Dynamic Systems, Pearson Publishing (6th ed). You are expected to **read** from the book, slides, and any assigned handouts or online sources.

**7. Course work:**

(a) **Assignments and Submissions:** Homework will be assigned on Canvas with specified due dates and requirements. **A single pdf file must be uploaded to Canvas.**

(b) **Preparation and submission of assignments:** Submitted work will not be accepted unless it is neatly prepared and organized. **Handwriting must be legible and dark enough to appear in scanned documents.** Any submission that is not legible or reasonably organized will not be graded. Late penalties may apply.

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<sup>1</sup>NOTE: This course is similar to courses offered as ECE 362K and ASE 370C

(c) **Late policy:** Late submissions will be dealt with on a case-by-case basis, and penalties will be applied if late submissions become common.

(d) **Make-ups:** Make-ups in HW or Quizzes will be handled on a case-by-case basis, but *prior* notice must be given except in cases of emergency.

(e) **Quizzes:** Short quizzes will be given in class (short answer/analysis, conceptual, closed-book).

(f) **Exams:** Dates for any exams appear on Canvas schedule; all exams are in-class, closed book/notes

**8. Grading:** Homework and any short quizzes = 35%, Exams = 40%, Final exam = 25%

**9. Attendance and behavior:** Class attendance and completion of homework assignments are expected. You are also expected to show respect and civility in all discussions with fellow students, administrators, and the course instructor.

**10. Academic Integrity:** University of Texas Honor Code - The core values of The University of Texas at Austin are learning, discovery, freedom, leadership, individual opportunity, and responsibility. Each member of the university is expected to uphold these values through integrity, honesty, trust, fairness, and respect toward peers and community. Each student in this course is expected to abide by this honor code. Any work submitted for academic credit must be the student's own work.

**11. Course outcomes:** This course addresses the following ABET program outcomes: 1, 6, 7. In particular, attention by the student should be given to Outcome 4, "Ability to set up and conduct experiments, and to present the results in a professional manner."

**12. Other University Notices and Policies:** Be familiar with the University's official email student notification policy. It is your responsibility to keep the University informed of changes in e-mail address. Students are expected to check Canvas and e-mail on a frequent and regular basis to stay current with University-related communications, recognizing that certain communications may be time-critical. (see <http://www.utexas.edu/its/help/utmail/1564>).

- *Accessibility Services.* UT provides, on request, appropriate academic adjustments for qualified students with disabilities. Any student with a documented disability (physical or cognitive) who requires academic accommodations should contact the Division of Campus and Community Engagement, Disability and Access (D&A), 512-471-6259,

<https://community.utexas.edu/disability>.

- *Mental Health and Wellness* UT also provides resources to support the well-being of your academic life and mental health, as well as counseling services.

- *Longhorn Wellness Center.* Creating a culture of student and campus well-being through programs, education, health messages, student engagement and collaboration.

<https://healthyhorns.utexas.edu/lwc/index.html>

- *Counseling and Mental Health Center.* <https://healthyhorns.utexas.edu/cmhc/> \*Providing mental health support through assessment and referral, group and individual counseling, psychiatry, and well-being services to the students of UT Austin.

- *Behavior Concerns Advice Line (BCAL).* If you are concerned about someone's behavior, use the Behavior Concerns Advice Line to discuss your concerns. Call 512-232-5050 or visit

<http://www.utexas.edu/safety/bcal>.

*Religious Holy Days:* University policy requires students to notify their instructors as far in advance of absence as possible so that arrangements can be made. You will have the opportunity to complete missed work in a reasonable time after your absence.

- *Drop Policy.* Contact the Graduate Advisor's office for information about drop policy.

**13. Proposed schedule of topics:** The schedule provided in Table 1 is a guide. Changes and/or adjustments to topics and assignments may be made based on the pace of the class and changes in content.

Table 1: **Projected** schedule of topics and assignments

| Week | Day | Topic(s)                                                                           | Assignment(s) |
|------|-----|------------------------------------------------------------------------------------|---------------|
| 1    |     | Introduction, definitions, models & feedback<br>Model formulations and conversions | HW 1<br>HW 2  |
| 2    |     | Equilibrium and linearization                                                      |               |
| 3    |     | Time-domain response<br>Time-domain specifications                                 | HW 3          |
| 4    |     | Feedback control relations                                                         |               |
| 5    |     | Poles, zeros, and stability                                                        | Exam 1        |
| 6    |     | Error and performance analysis<br>PID control                                      |               |
| 7    |     | Root locus<br>Root locus; compensator design                                       | HW 4          |
| 8    |     | Design applications                                                                |               |
| 9    |     | Frequency domain response (using Bode)<br>Nyquist stability criterion              | HW 5          |
| 10   |     | Compensation, loop shaping<br>Application examples                                 |               |
| 11   |     | State-space analysis and design<br>Pole placement                                  | HW 6          |
| 12   |     | Optimal control<br>Estimation/observers                                            |               |
| 13   |     | Compensation in state-space<br>Application examples                                | Exam 2        |
| 14   |     | Fall break<br>Thanksgiving Holiday                                                 |               |
| 15   |     | Review<br>Review                                                                   |               |
| –    |     | Final exam (per university schedule)                                               | Final exam    |