A Multiscale Cohesive Zone Model for Rate Dependent Fracture of Interfaces Tianhao Yang, Kenneth M. Liechti and Rui Huang

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Congratulations Ravi!

J. Mech. Phys. Solids 145, 104142 (2020).



Rate-dependent fracture of interfaces



Rate-dependent fracture of a silicon/epoxy interface



T. Yang, et al., J. Mech. Phys. Solids 131, 1-19 (2019).

A multiscale modeling approach



The University of Texas at Austin Aerospace Engineering and Engineering Mechanics Cockrell School of Engineering Interfacial traction and separation:

$$\delta = \lambda_n n r_0$$

$$\sigma = \int (1 - D_n) \rho_0(n) f(\lambda_n) dn$$

Damage evolution (thermally activated):

$$\frac{dD_n}{dt} = \frac{n}{t_0} (1 - D_n) \exp\left(-\frac{E_b}{k_B T}\right)$$

• An energy barrier:

$$E_b = E_b(f) \text{ or } E_b(\lambda_n)$$



Bond model (Kuhn segment)



2 bond parameters:

- $r_0 \rightarrow$ equilibrium bond length
- $\varepsilon_0 \rightarrow \text{bond energy}$

- 3 key features for a simple bond model:
- (1) The potential energy is minimized at an equilibrium bond length;
- (2) The potential energy becomes infinitely high as the two atoms approach each other;
- (3) The potential energy approaches zero as the two atoms are separated far apart from each other.

Chain model A freely jointed chain with stretchable bonds

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Kinetics of thermally activated chain scission

 $=\lambda nr_0$ ŝ x

 $\sigma = Nf = (1 - D)N_0 f(\delta)$

Assume a constant chain length (*n*) for now.

Bond survival probability $R_b = N/N_0$

$$\frac{R_b}{R_b} = -\frac{1}{t_0} \exp\left(-\frac{E_b}{k_B T}\right)$$

Chain survival probability

$$\frac{\dot{R}_{chain}}{R_{chain}} = -\frac{n}{t_0} \exp\left(-\frac{E_b}{k_B T}\right)$$

Damage evolution

 $D = 1 - R_{chain}$

 $R_{chain} = R_h^n$

What is the activation energy or energy barrier?

A microscopic time scale:

 $t_0 \sim \frac{\hbar}{k_B T} \sim 10^{-13} \text{ s}$

Is this relevant?

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 $\frac{dD}{dt} = \frac{n}{t_0} (1 - D) \exp\left(-\frac{E_b}{k_B T}\right)$

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$E_{\text{pullibrium position}} = f_2 > f_1$

Energy barrier for chain scission

Transition-state theory: The transition from an equilibrium state of the chain to the state of a broken chain (with one broken bond) may be traversed along a path with the minimum energy barrier in the energy landscape.



- An external force lowers the energy barrier (nonlinearly) for chain scission.
- The energy barrier becomes zero at the peak force for each chain.
- Reverse transition (healing) is possible under displacement control.

Rate-dependent traction-separation relations





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Rate-dependent interfacial properties

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- The initial stiffness is *independent* of the separation rate.
- Both strength and toughness increase with increasing rates.
- The predicted toughness is always less than that by the Lake-Thomas model ($\overline{\Gamma} = \overline{\varepsilon}$).



Effect of statistically distributed chain lengths

 $\sigma = \int (1 - D_n) f(\lambda_n) \rho_0(n) dn$ $\frac{dD_n}{dt} = \frac{n}{t_0} (1 - D_n) \exp\left(-\frac{E_b}{k_B T}\right)$

The shorter chains break earlier, leading to lower strength. The presence of longer chains extends the range of separation.





Effect of chain length distribution on interfacial properties

 $\bar{\chi} = \frac{\chi}{n_0}$



- Interfacial stiffness: increases slightly, independent of rate
- Interfacial strength: decreases significantly with the relative deviation at fast rate
- Interfacial toughness: less sensitive to the chain length distribution

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Finite element implementation (ABAQUS/UINTER)





Model parameters:

- Bond length ($r_0 \sim 0.5$ nm)
- Bond energy ($\varepsilon_0 \sim 1 \text{ eV}$)
- Average chain length ($n_0 \sim 4000$)
- Chain length deviation ($\chi \sim 230$)
- Chain areal density ($N_0 \sim 8 \times 10^{17} \text{ m}^{-2}$)
- Microscopic time scale ($t_0 \sim 10^{-13}$ s)









Summary



- A multiscale, mechanism-based cohesive zone model was proposed for rate-dependent fracture of polymer interfaces, potentially linking the interfacial properties (i.e., stiffness, strength and toughness) to the molecular structures.
- Model parameters were determined by direct comparation to the DCB experiments.
- The predicted traction-separation relation depends on the <u>local</u> separation rate and the loading history (e.g., non-monotonic or cyclic).



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