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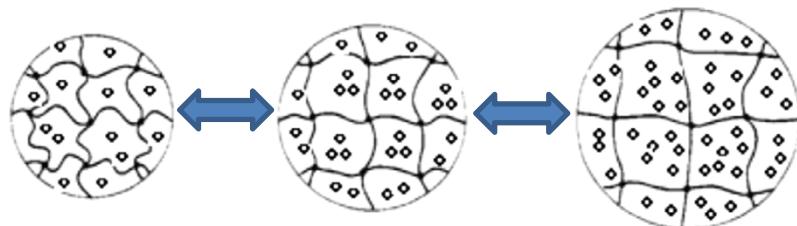
# **Large Deformation of Hydrogels Coupled with Solvent Diffusion**

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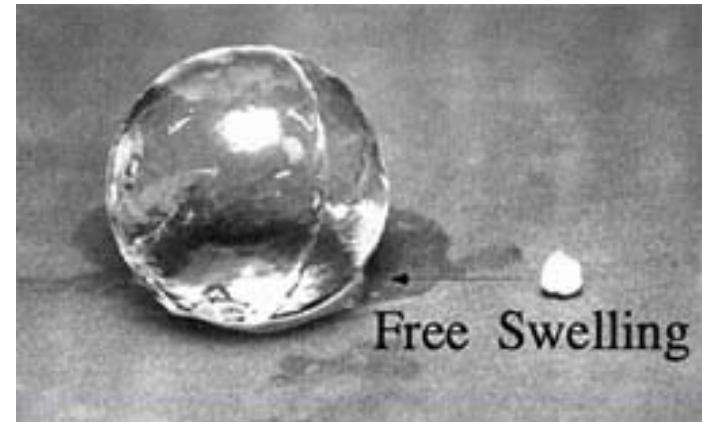
# Hydrogel = polymer + water (solvent)



Crosslinked  
polymer



Solvent  
molecules

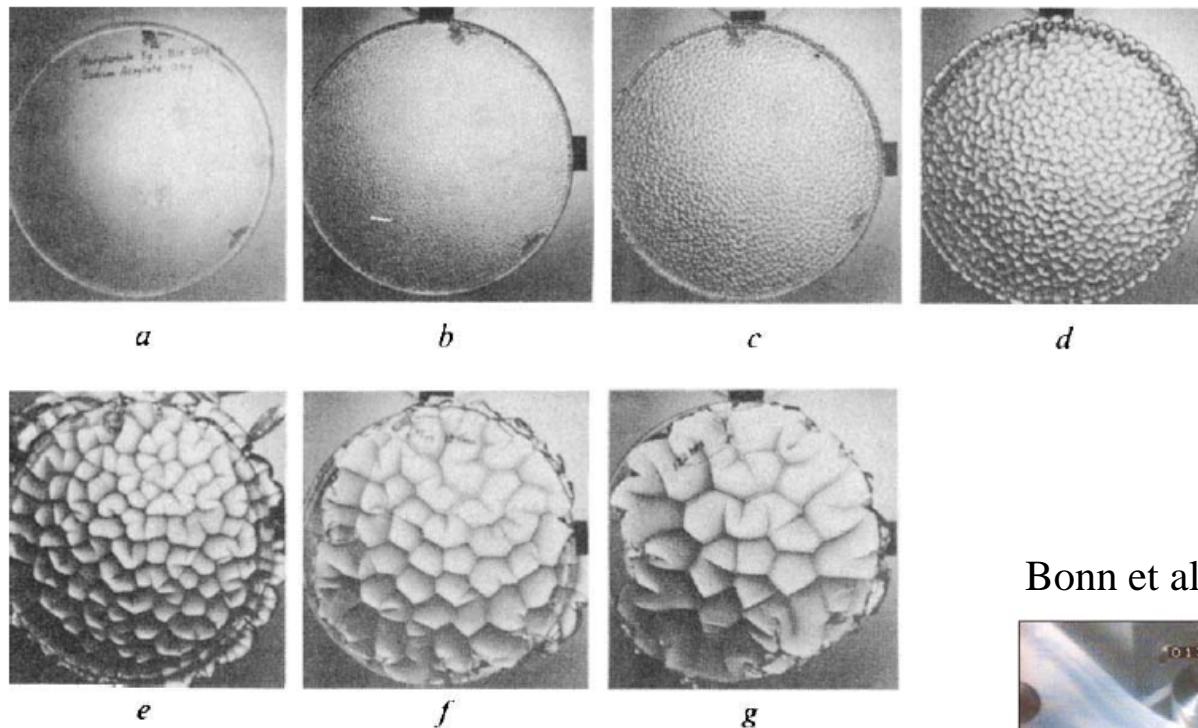


Ambrosio 2010

- Large and reversible deformation facilitated by solvent migration
- Response to mechanical/chemical/electrical stimuli
- Applications: biomedical, soft machines/robots

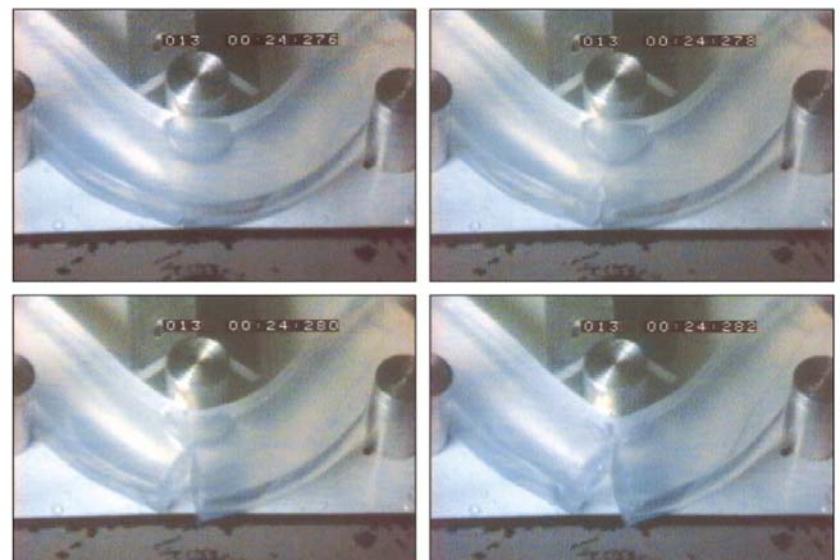
# Transient behaviors of hydrogels

Tanaka et al, 1987

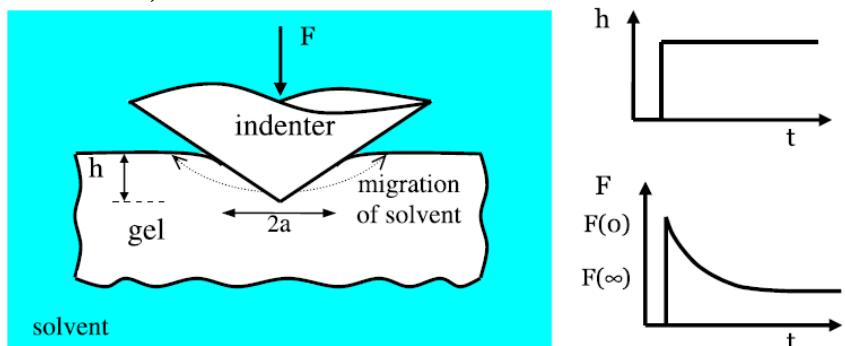


- Swelling
- Indentation
- Fracture
- ...

Bonn et al, 1998



Hu et al, 2011



# Linear Poroelasticity

$$\frac{\partial \sigma_{ij}}{\partial x_j} + b_i = 0$$

$$\varepsilon_{ij} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

- Linear constitutive relation
- Linear kinematics
- Linear kinetics
- Inertia ignored

$$J_k = -\frac{k}{\eta} \frac{\partial p}{\partial x_k}$$

$$\frac{\partial \phi}{\partial t} = \frac{k}{\eta} \frac{\partial^2 p}{\partial x_k \partial x_k}$$

$$\sigma_{ij} = 2G \left[ \varepsilon_{ij} + \frac{\nu}{1-2\nu} \varepsilon_{kk} \delta_{ij} \right] - p \delta_{ij}$$

$$\varepsilon_{kk} = \phi - \phi_0$$

3 material parameters:  $G, \nu, k/\eta$

# A Nonlinear Continuum Theory for Gels

Free energy density function:

$$U(\mathbf{F}, \mathbf{C})$$

Nominal stress:

$$s_{iK} = \frac{\partial U}{\partial F_{iK}}$$

Chemical potential:

$$\mu = \frac{\partial U}{\partial C}$$

Mechanical equilibrium:

$$\frac{\partial s_{iK}}{\partial X_K} + B_i = 0$$

Diffusion kinetics:

$$J_K = -\frac{DC}{k_B T} \left( \frac{\partial X_K}{\partial x_k} \frac{\partial X_L}{\partial x_k} \right) \frac{\partial \mu}{\partial X_L} = -M_{KL} \frac{\partial \mu}{\partial X_L}$$

Conservation of solvent molecules:

$$\frac{\partial C}{\partial t} = -\frac{\partial J_K}{\partial X_K} = \frac{\partial}{\partial X_K} \left( M_{KL} \frac{\partial \mu}{\partial X_L} \right)$$

- Nonlinear constitutive relations
- Nonlinear kinematics
- Geometrically nonlinear kinetics
- Inertia ignored

# A Material Model

Flory-Rehner (1943) free energy density function:

$$U(\mathbf{F}, C) = U_e(\mathbf{F}) + U_m(C)$$

- Neo-Hookean rubber elasticity:

$$U_e(\mathbf{F}) = \frac{1}{2} N k_B T [F_{iK} F_{iK} - 3 - 2 \ln(\det(\mathbf{F}))]$$

- Flory-Huggins polymer solution theory:

$$U_m(C) = \frac{k_B T}{\Omega} \left( \Omega C \ln \frac{\Omega C}{1 + \Omega C} + \frac{\chi \Omega C}{1 + \Omega C} \right)$$

- Volume of gel:

$$\det(\mathbf{F}) = 1 + \Omega C$$



$$U(\mathbf{F}, C) = U_e(\mathbf{F}) + U_m(C) + \Pi(1 + \Omega C - \det(\mathbf{F}))$$

4 material parameters:  $Nk_B T, N\Omega, \chi, D$

# Linearization near a swollen state

Isotropic swollen state:  $\lambda_1 = \lambda_2 = \lambda_3 = \lambda_0$

$$\frac{\mu_0}{k_B T} = \ln \frac{\lambda_0^3 - 1}{\lambda_0^3} + \frac{1}{\lambda_0^3} + \frac{\chi}{\lambda_0^6} + N\Omega \left( \frac{1}{\lambda_0} - \frac{1}{\lambda_0^3} \right)$$

$$\sigma_{ij} = 2G \left[ \epsilon_{ij} + \frac{\nu}{1-2\nu} \epsilon_{kk} \delta_{ij} \right] - \frac{\mu - \mu_0}{\Omega} \delta_{ij}$$

$$j_k = -\frac{c_0 D}{k_B T} \frac{\partial \mu}{\partial x_k} = -M_0 \frac{\partial \mu}{\partial x_k}$$

$$\frac{\partial c}{\partial t} = -\frac{\partial j_k}{\partial x_k} = M_0 \frac{\partial^2 \mu}{\partial x_k \partial x_k}$$

$$\epsilon_{kk} = \Omega(c - c_0) \quad \Omega c_0 = 1 - \lambda_0^{-3}$$

$$G = \frac{Nk_B T}{\lambda_0}$$

$$\nu = \frac{1}{2} - \frac{N\Omega}{2} \left[ \frac{1}{\lambda_0^2(\lambda_0^3 - 1)} + \frac{N\Omega}{\lambda_0^2} - \frac{2\chi}{\lambda_0^5} \right]^{-1}$$

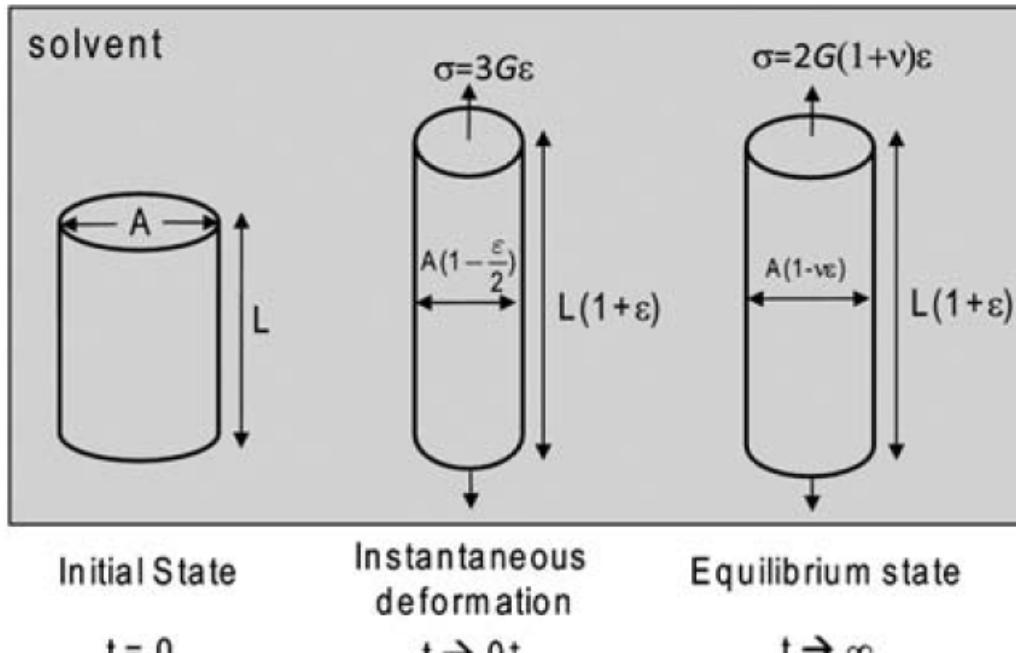
$$M_0 = \frac{D}{\Omega k_B T} \frac{\lambda_0^3 - 1}{\lambda_0^3}$$

- The linearized equations are identical to the theory of linear poroelasticity.
- The 3 parameters in the linearized equations depend on the swelling ratio.

$$p \Leftrightarrow \frac{\mu - \mu_0}{\Omega} \quad \phi \Leftrightarrow \Omega c \quad \frac{k}{\eta} \Leftrightarrow \frac{D}{k_B T} \frac{\lambda_0^3 - 1}{\lambda_0^3}$$

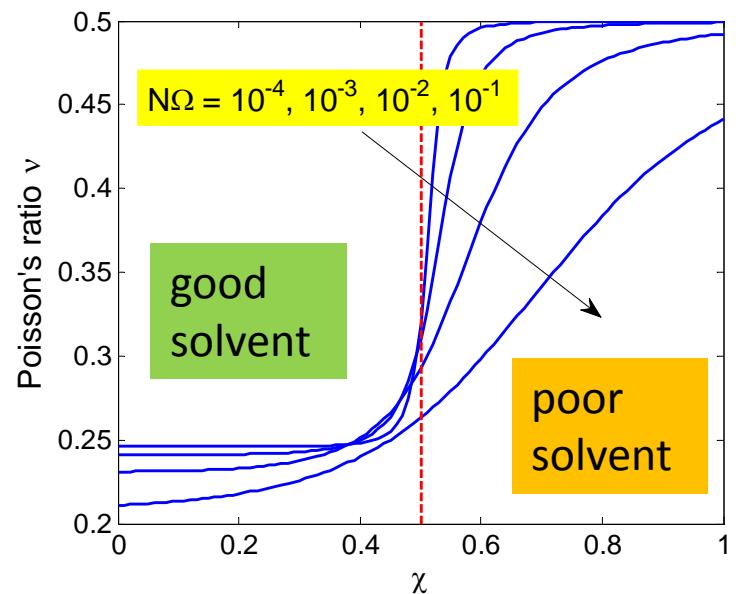
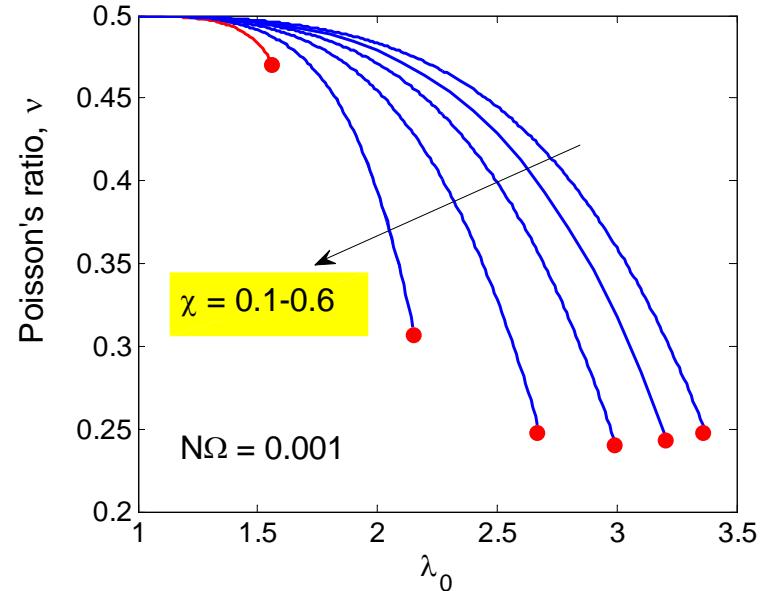
# Poisson's ratio

Yoon et al., Soft Matter 6, 6004-6012 (2010).



$$\nu = \frac{1}{2} - \frac{N\Omega}{2} \left[ \frac{1}{\lambda_0^2(\lambda_0^3 - 1)} + \frac{N\Omega}{\lambda_0^2} - \frac{2\chi}{\lambda_0^5} \right]^{-1}$$

- Instantaneously incompressible ( $\nu_0 = 0.5$ )
- The equilibrium Poisson's ratio depends on the initial state ( $\lambda_0$  or  $\mu_0$ ) as well as the intrinsic material properties ( $\chi$  and  $N\Omega$ ).



Boukla and Huang, Soft Matter 2012.

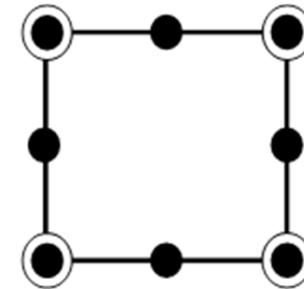
# A nonlinear, transient finite element method

Weak form for the coupled fields:

$$\int_{V_0} \left( s_{iJ} \delta u_{i,J} - C \delta \mu + \Delta t J_K \delta \mu_{,K} \right) dV = \int_{V_0} \left( b_i \delta u_i - r \Delta t \delta \mu - C^t \delta \mu \right) dV + \int_{S_0} T_i \delta u_i dS - \int_{S_0} i \Delta t \delta \mu dS$$

Discretization

$$\begin{aligned} \mathbf{u} &= \mathbf{N}^u \mathbf{u}^n & \boldsymbol{\delta u} &= \mathbf{N}^u \boldsymbol{\delta u}^n \\ \boldsymbol{\mu} &= \mathbf{N}^\mu \boldsymbol{\mu}^n & \boldsymbol{\delta \mu} &= \mathbf{N}^\mu \boldsymbol{\delta \mu}^n \end{aligned}$$



- For numerical stability, the 2D Taylor-Hood elements (8u4p) are implemented.

A slightly different material model:

$$U(\mathbf{F}, C) = U_e(\mathbf{F}) + U_m(C) + U_c(F, C)$$

$$U_c(\mathbf{F}, C) = K \frac{(\det(\mathbf{F}) - 1 - \Omega C)^2}{2}$$

Legendre transform

$$\hat{U}(\mathbf{F}, \boldsymbol{\mu}) = U(\mathbf{F}, C) - \boldsymbol{\mu} C$$

Bouklas et al., JMPS 2015

# Numerical stability for mixed finite element method

- Nearly incompressible behavior at the instantaneous response limit  $t \rightarrow 0$  for  $K \gg Nk_B T$
- Discontinuity of the boundary condition at  $t = 0^+$  with respect to the initial conditions

Choice of appropriate interpolations:

LBB condition

(Ladyzhenskaya-Babuska-Brezzi)

● Displacement node

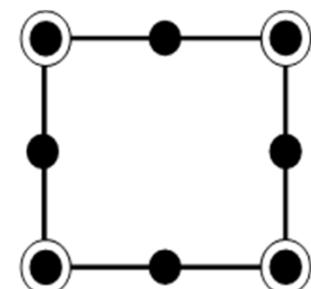
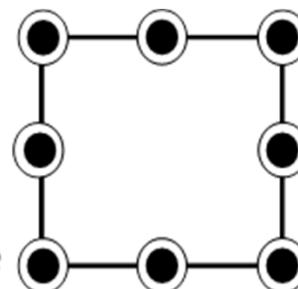
○ Chemical potential node

**UNSTABLE**

Equal order  
8u8p

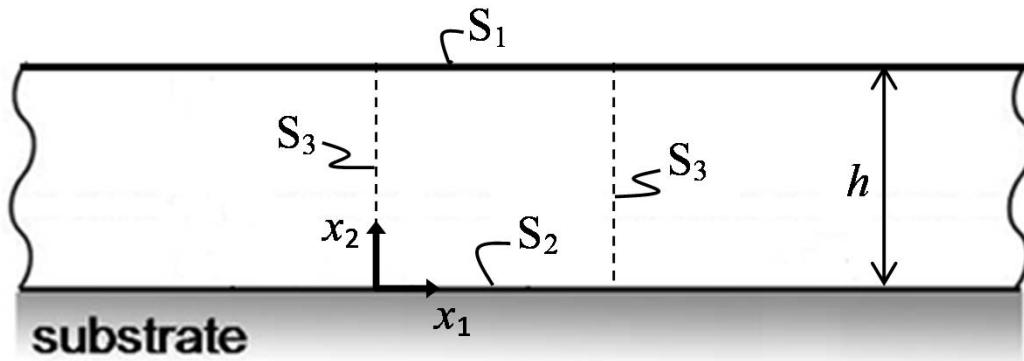
**STABLE**

Taylor Hood  
8u4p



- Incompressible linear elasticity
- Stokes flow
- Linear poroelasticity

# Constrained swelling of hydrogel layers



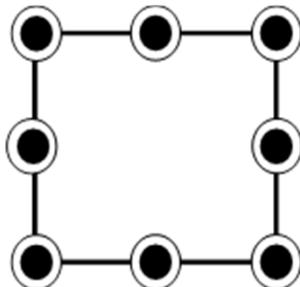
IC's

$$\begin{aligned} \mathbf{u}(\mathbf{X}, 0) &= \lambda_0 \mathbf{X} - \mathbf{X} \\ \mu(\mathbf{X}, 0) &= \mu_0 \end{aligned}$$

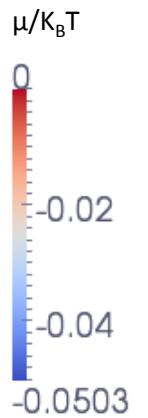
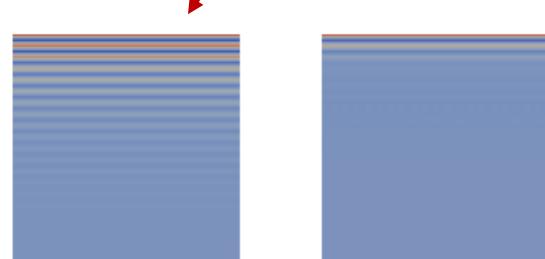
BC's

$$\begin{aligned} S_1 : \mu &= 0 \\ S_2 : \Delta \mathbf{u} &= \mathbf{0}, J_2 = 0 \\ S_3 : \Delta u_1 &= 0, J_1 = 0 \end{aligned}$$

**UNSTABLE**  
Equal order  
8u8μ element



Oscillations in  
the early stage

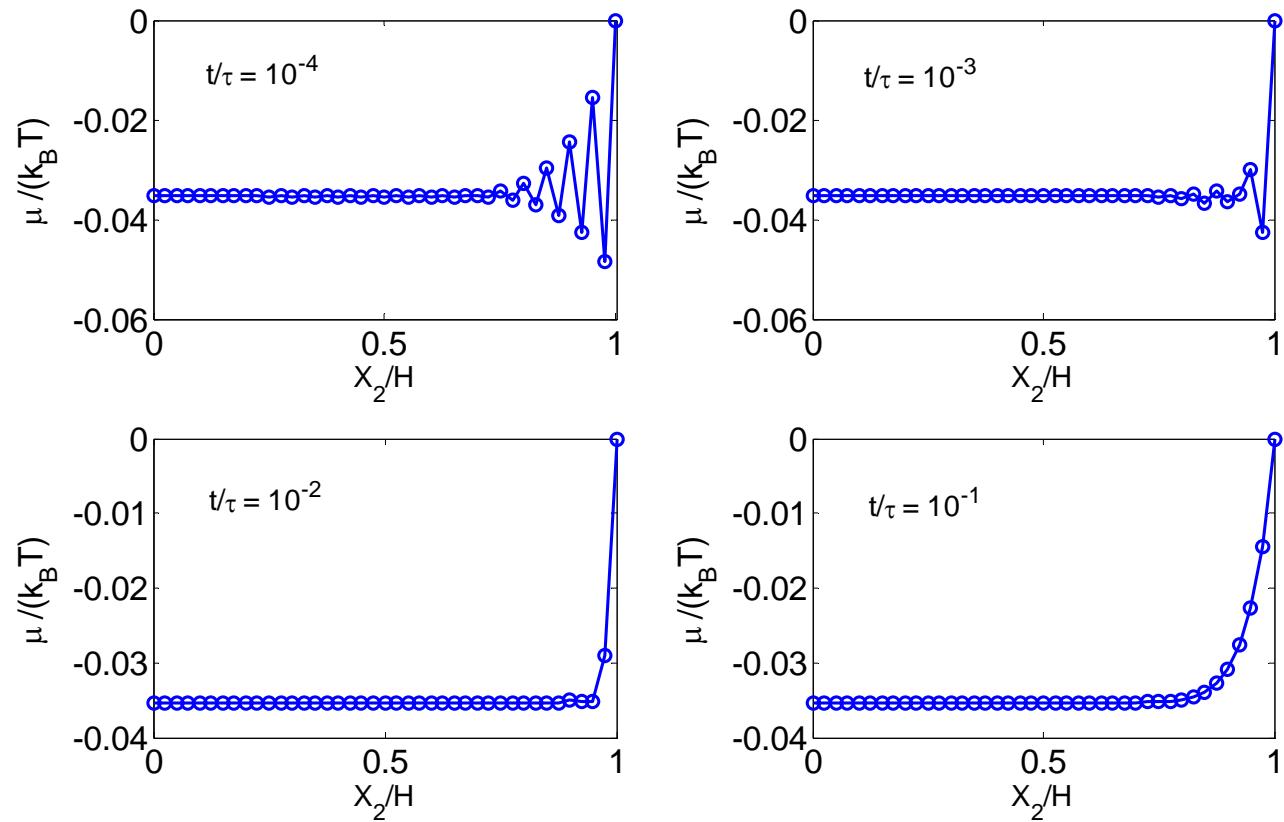
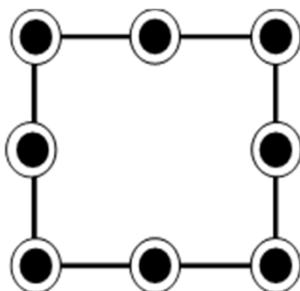


time

# Evolution of chemical potential oscillations

**UNSTABLE**

$8u8\mu$



$$\tau = \frac{H^2}{D}$$

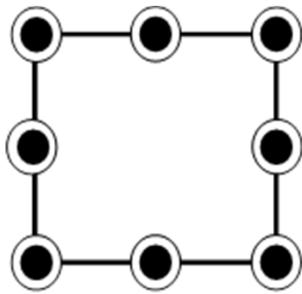
$$\lambda_0 = 1.4, N\Omega = 0.001$$

$$\chi = 0.4, K = 10^3 N k_B T$$

# Effect of compressibility

**UNSTABLE**

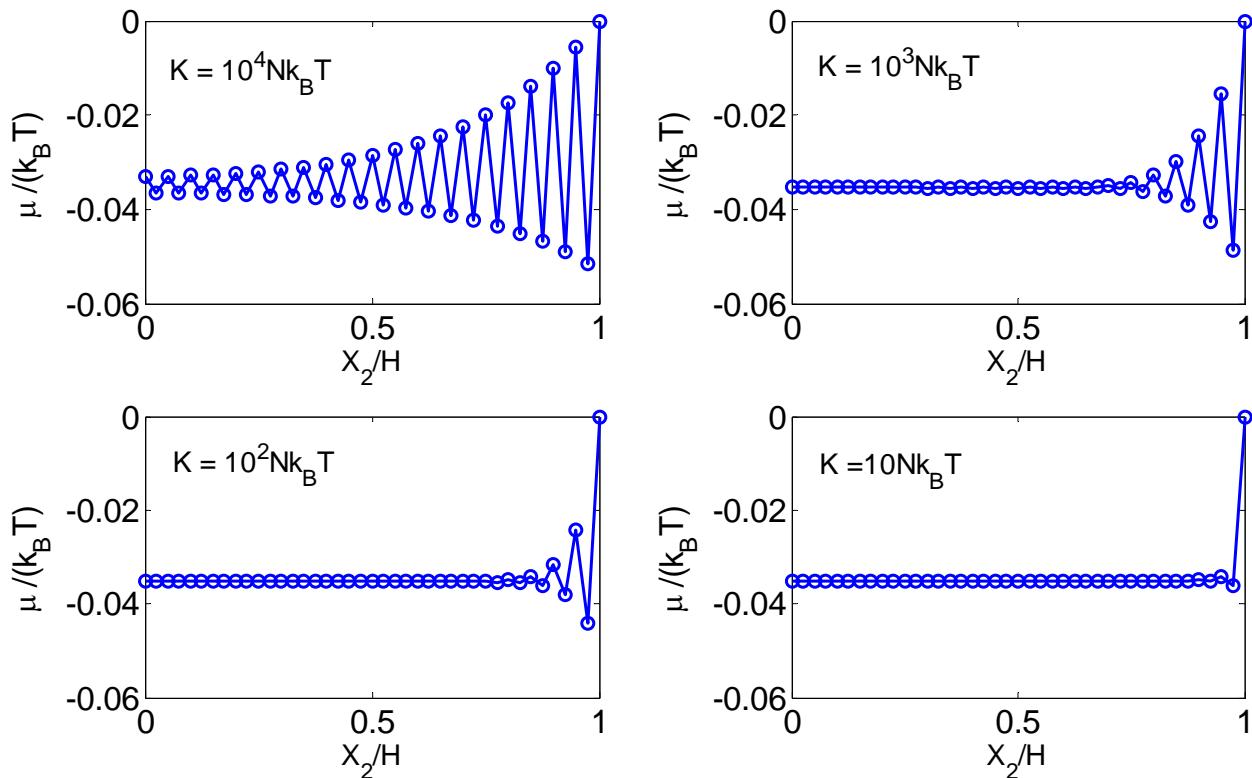
$8\mu$



$$\lambda_0 = 1.4, N\Omega = 0.001$$

$$\chi = 0.4$$

$$t / \tau = 10^{-4}$$

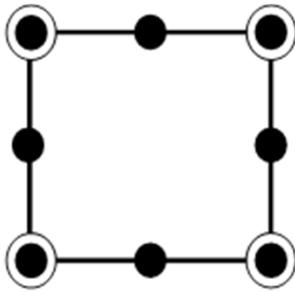


The oscillations decrease with increasing  
compressibility ( $K$  decreasing)

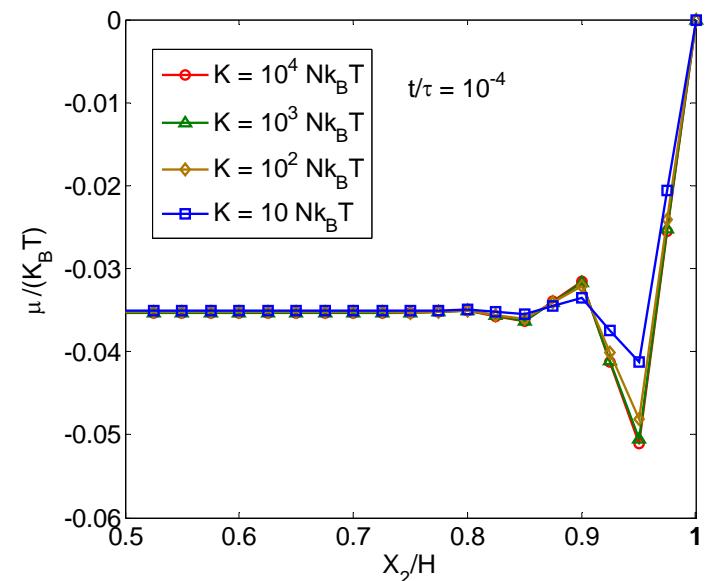
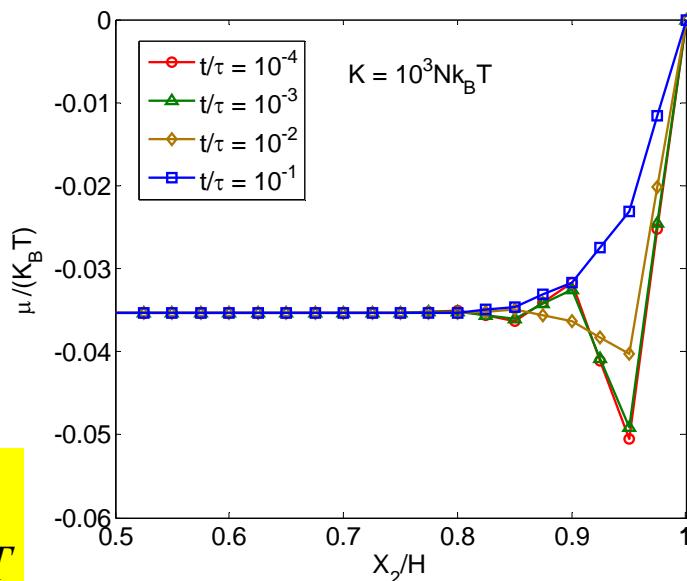
# Use of stable interpolation

**STABLE**

Taylor Hood  
8u4 $\mu$  element

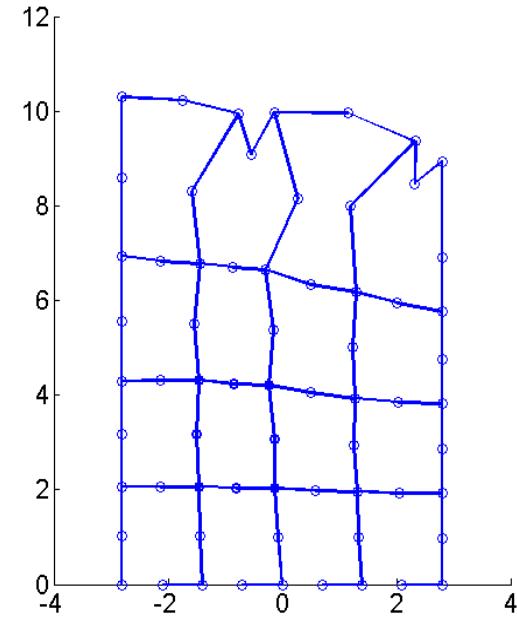
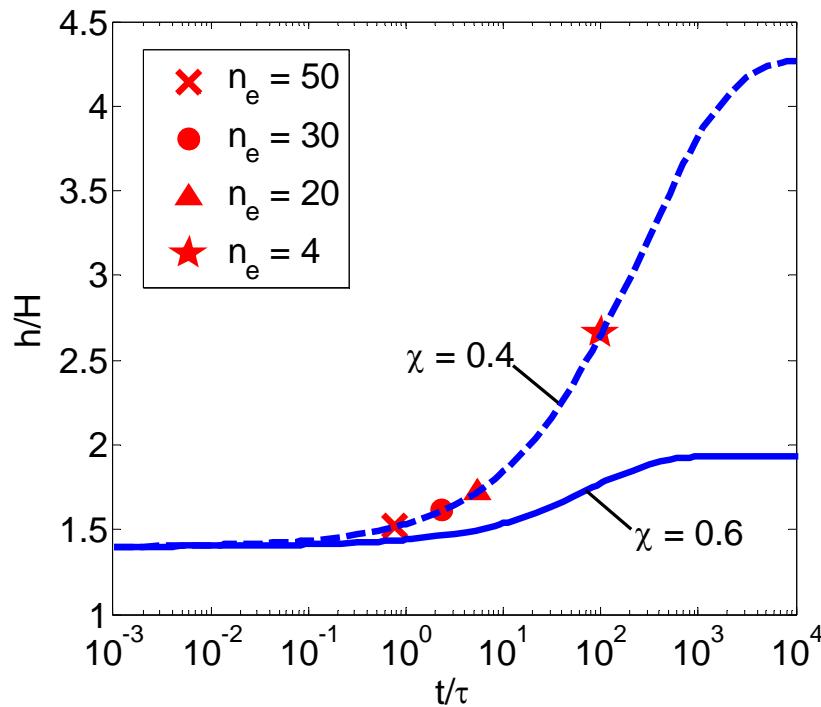


$$\begin{aligned}\lambda_0 &= 1.4, N\Omega = 0.001 \\ \chi &= 0.4, K = 10^3 Nk_B T\end{aligned}$$



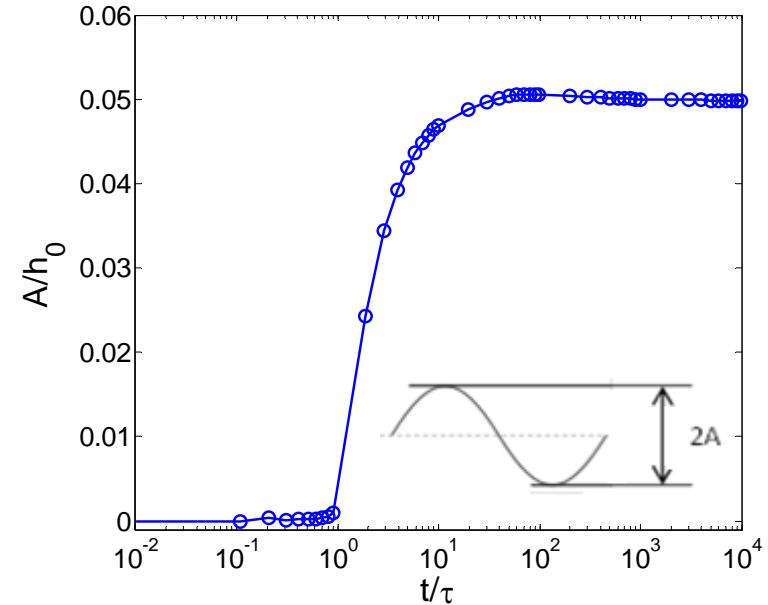
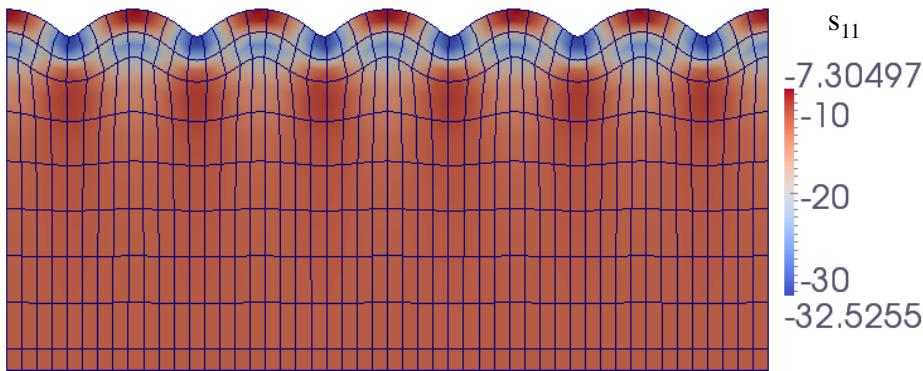
- Oscillations are significantly reduced and do not depend on compressibility.
- The remaining oscillations are due to discontinuity of the boundary condition at  $t = 0^+$ .

# Swelling induced surface instability



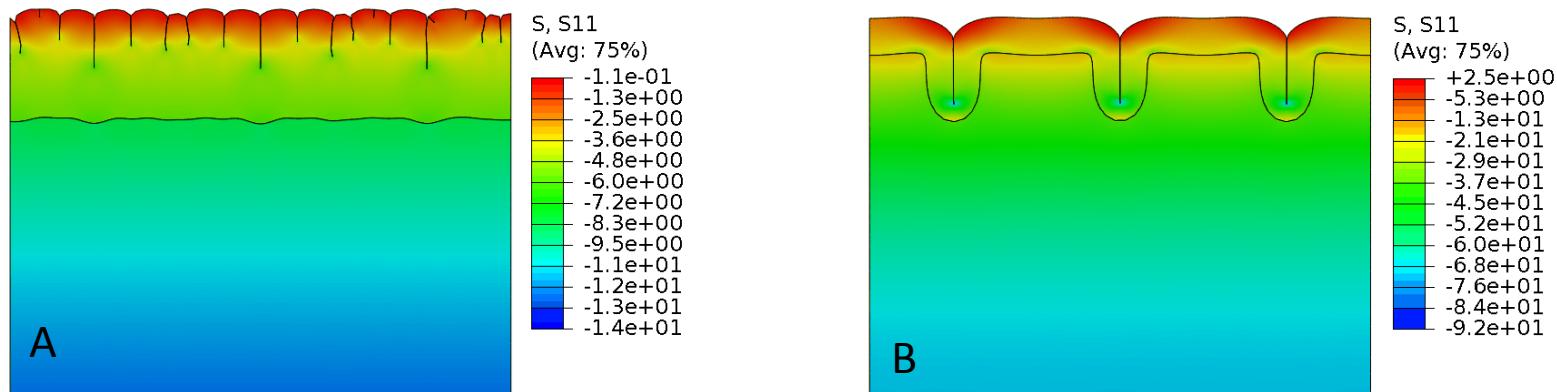
- Swell induced compressive stress could lead to surface instability
- For a poor solvent ( $\chi = 0.6$ ), the surface remains flat and stable.
- For a good solvent ( $\chi = 0.4$ ), the homogeneous hydrogel layer is instantaneously unstable upon swelling; numerically, divergence occurs at a finite time that depends on the mesh size.

# Swell induced surface wrinkling



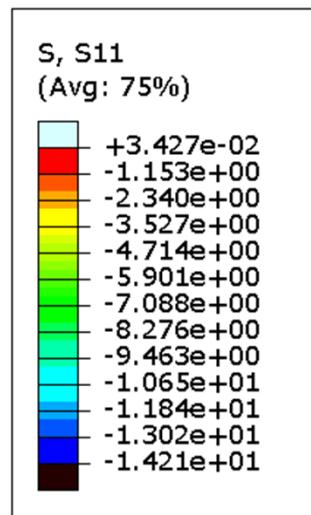
- Regularization of the surface instability by using a stiff skin layer.
- Wrinkle amplitude grows over time, with a selected wrinkle wavelength.

# Two types of surface instability



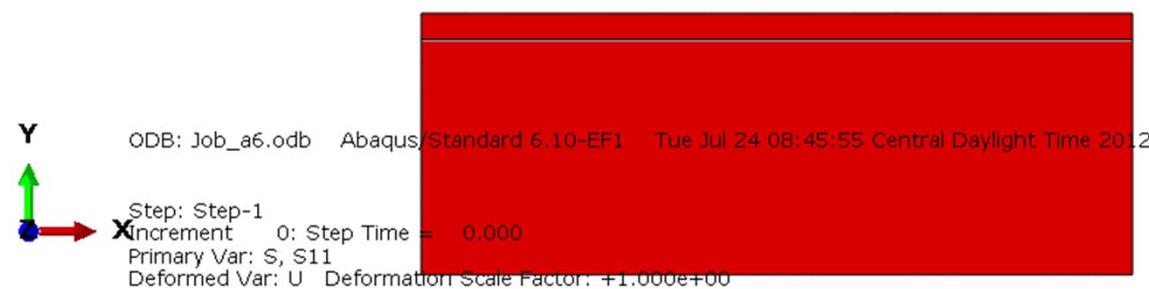
- **Type A:** soft-on-hard bilayer, critical condition at the short wave limit, forming surface creases;
- **Type B:** hard-on-soft bilayer, critical condition at a finite wavelength, forming surface wrinkles first.

# A soft-on-hard gel bilayer (Type A)

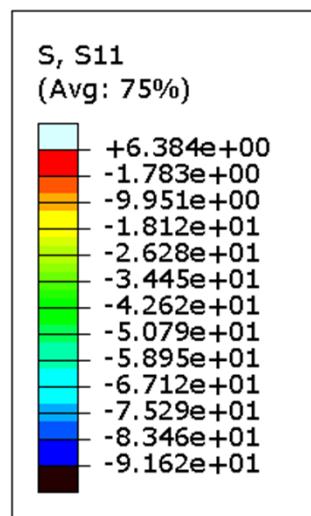


Step: Step-1 Frame: 0  
Total Time: 0.000000

X  
Y  
Z



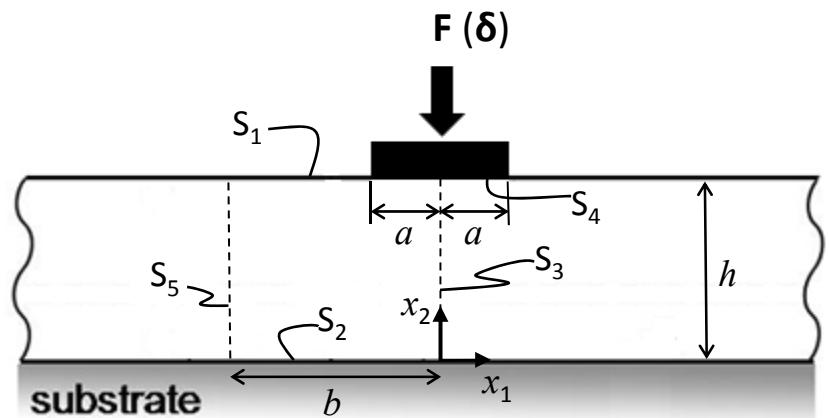
# A hard-on-soft gel bilayer (Type B)



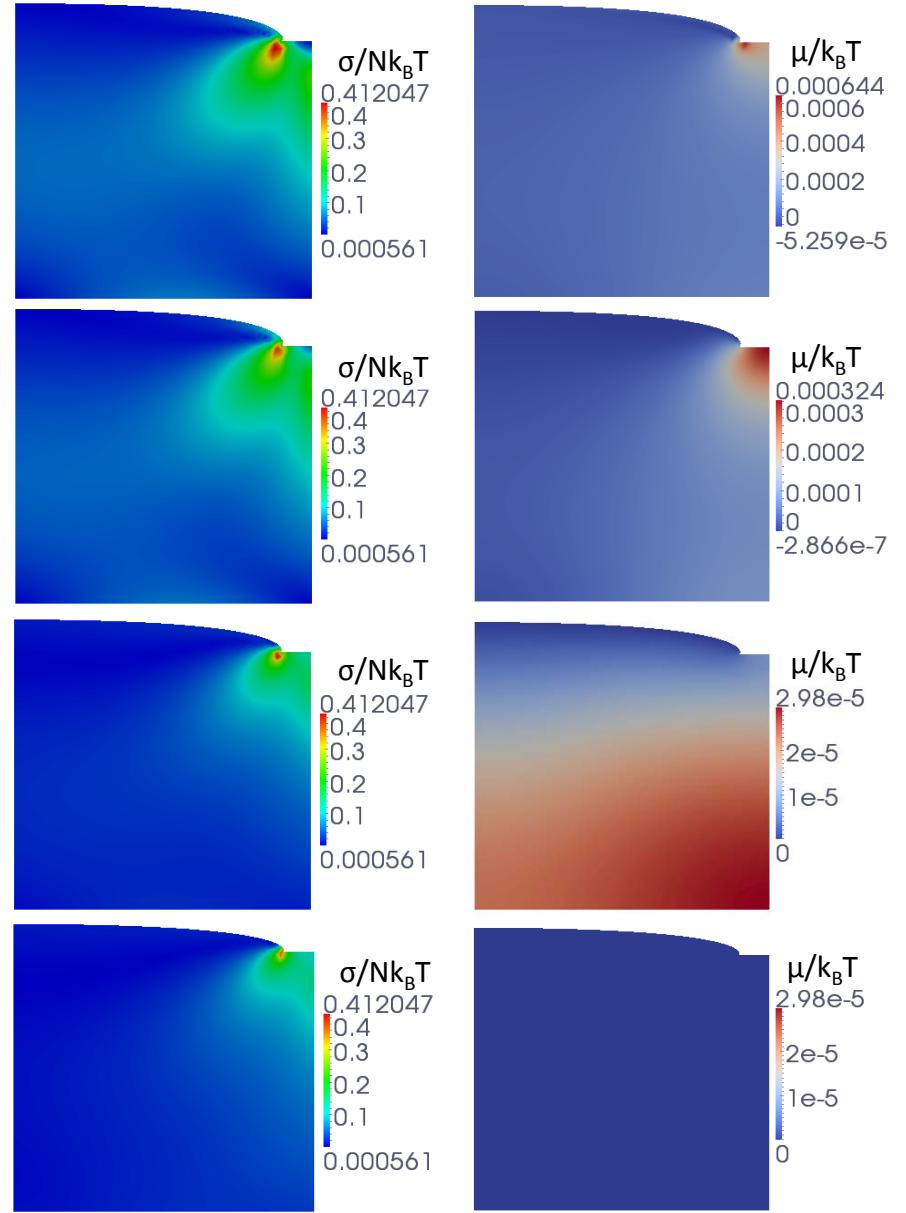
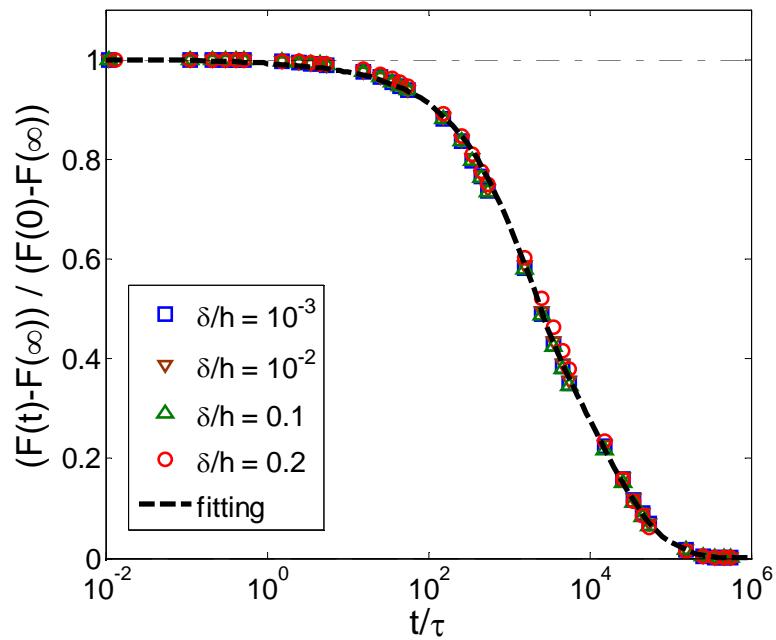
Step: Step-1 Frame: 0  
Total Time: 0.000000



# Flat Punch Indentation

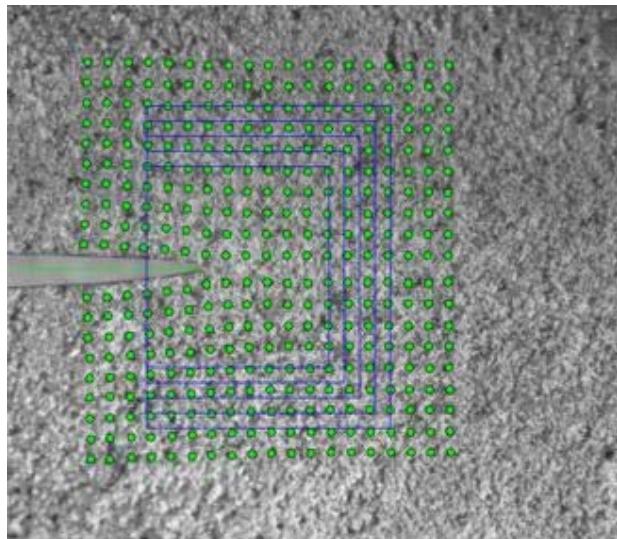


$$\bar{F}(t) = (F(t) - F(\infty)) / (F(0) - F(\infty)) \quad \tau = \frac{\alpha^2}{D}$$

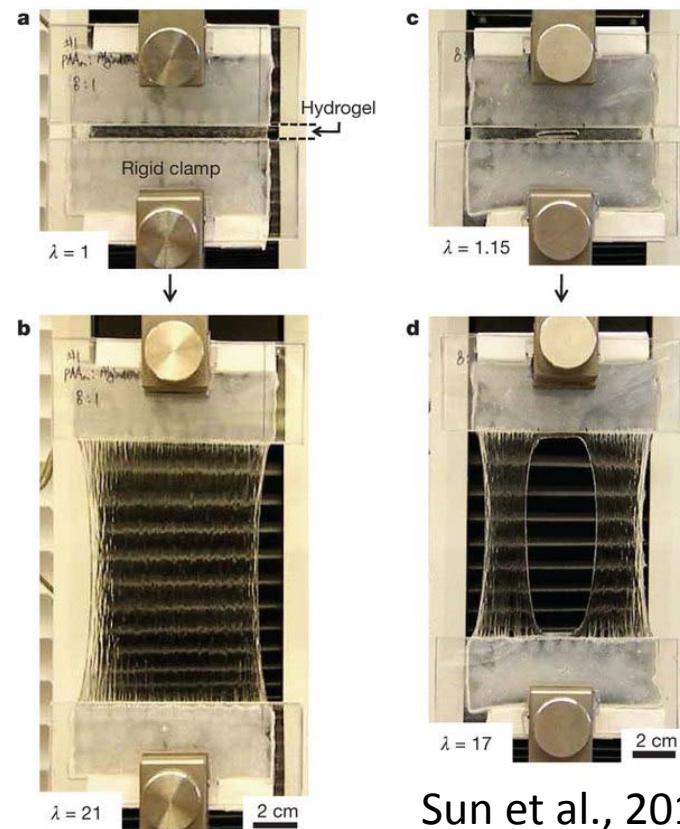


# Fracture Properties of Hydrogels

- Reported values of fracture toughness range from 1 to 10000 J/m<sup>2</sup>
- Fracture mechanism may vary over different types of hydrogels
- Potential rate dependence may relate to viscoelasticity or solvent diffusion
- Experimental methods to measure fracture properties of hydrogels are not well developed.

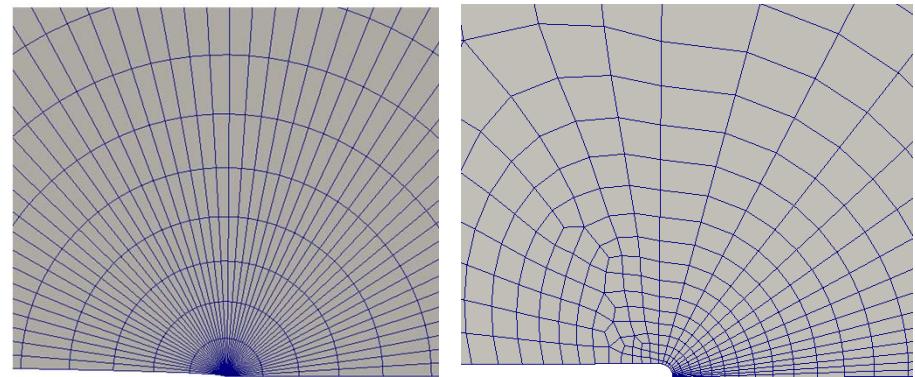
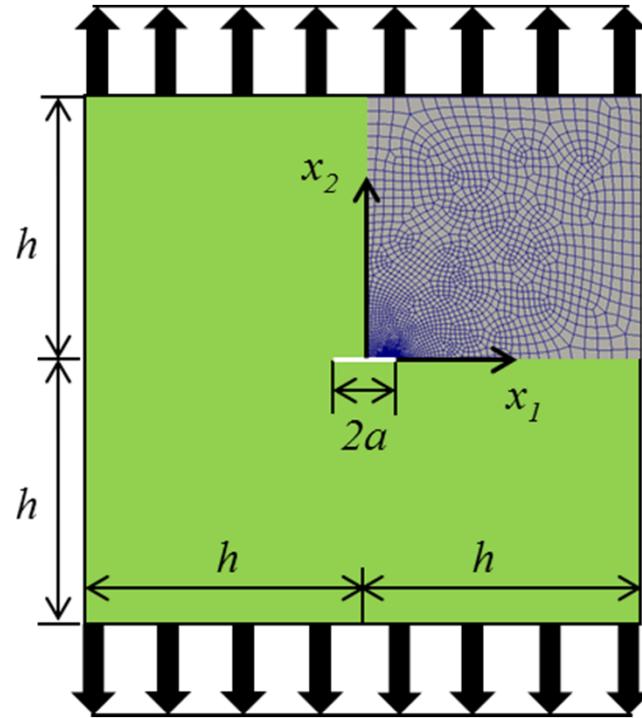


Kwon et al., 2011.



Sun et al., 2012.

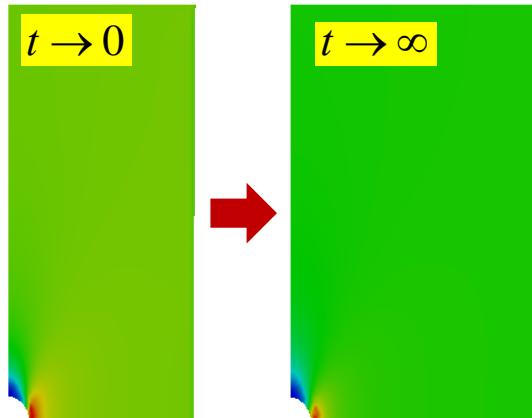
# A center crack model



- Consider a center crack in a hydrogel plate under remote strain
- A nonlinear, transient finite element method is employed
- Sharp and notched crack geometries are used for small to large deformation

Bouklas et al., JAM 2015

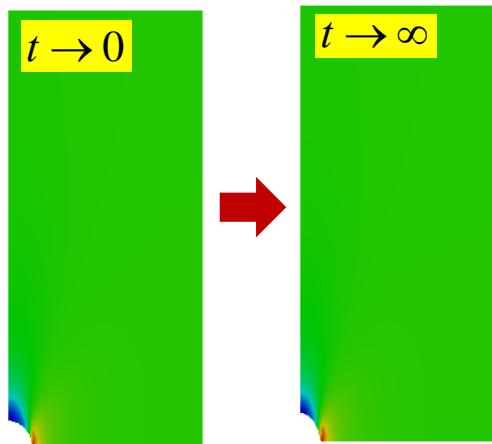
# Immersed and not-immersed cases



- Hydrogel is immersed in solvent
- Assume solvent-permeable boundaries and crack faces

$$\nu_0 = 0.5$$

$$\nu_\infty = \frac{1}{2} - \frac{N\Omega}{2} \left[ \frac{1}{\lambda_0^2(\lambda_0^3 - 1)} + \frac{N\Omega}{\lambda_0^2} - \frac{2\chi}{\lambda_0^5} \right]^{-1}$$



- Hydrogel is not immersed in solvent
- Assume solvent-impermeable boundaries and crack faces
- Overall volume is conserved, but solvent redistribution within the gel may lead to local volume change.

# LEFM Predictions

Crack-tip stress field:

$$\sigma_{ij}(r, \theta) = \frac{K_I}{\sqrt{2\pi r}} f_{ij}^I(\theta) + T \delta_{1i} \delta_{1j}$$

$$K_I = \sigma_\infty \sqrt{\pi a} \quad T = -\sigma_\infty$$

$$\sigma_\infty = \frac{2G\varepsilon_\infty}{1-\nu}$$

Stress would relax over time

$$G = \frac{Nk_B T}{\lambda_0}$$

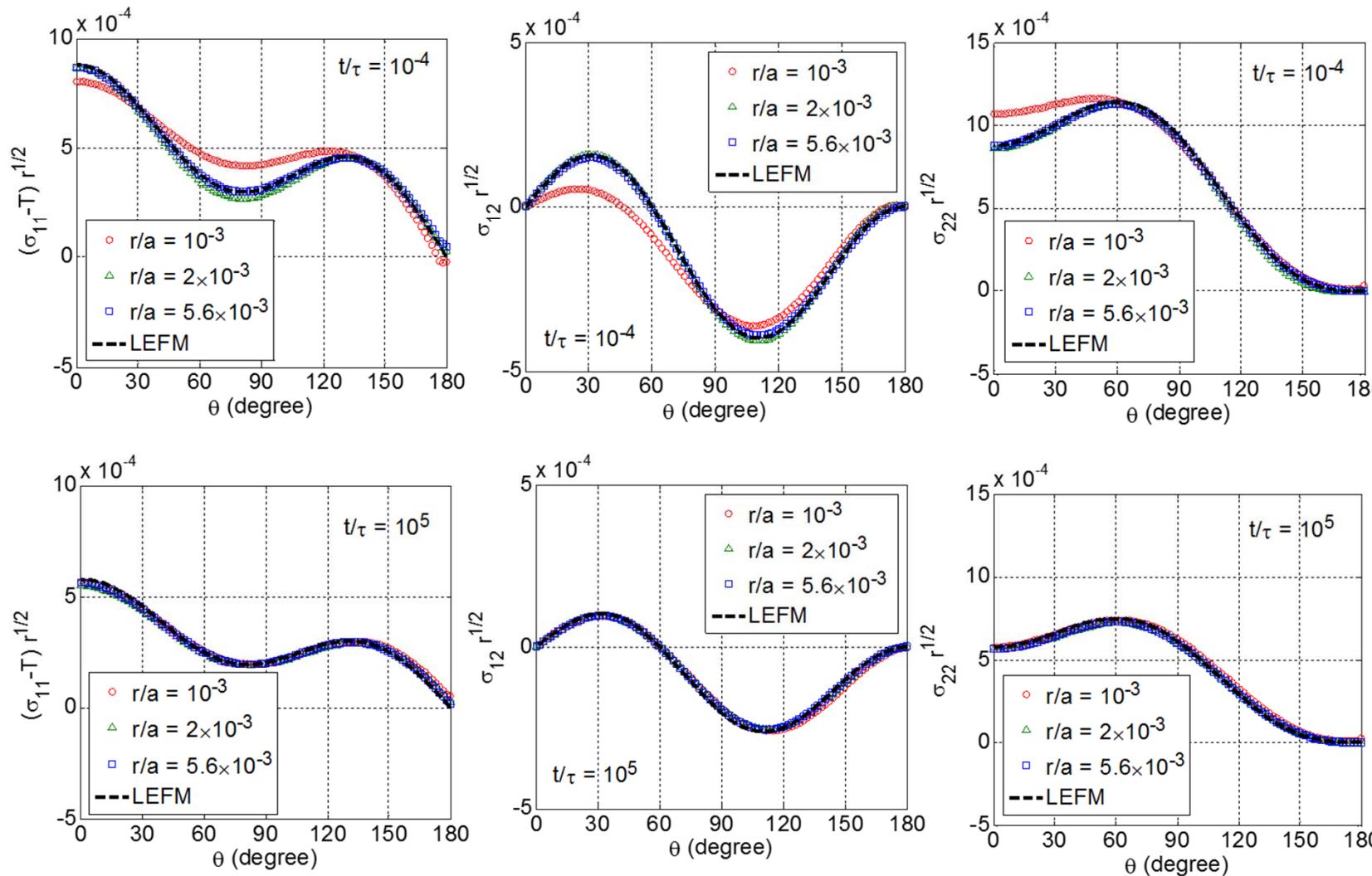
Crack opening:

$$\hat{u}_2(x_1) = 2\varepsilon_\infty \sqrt{a^2 - x_1^2}$$

Crack opening would remain constant,  
independent of modulus or Poisson's ratio

# Crack-tip stress fields

$$\varepsilon_\infty = 10^{-3}$$



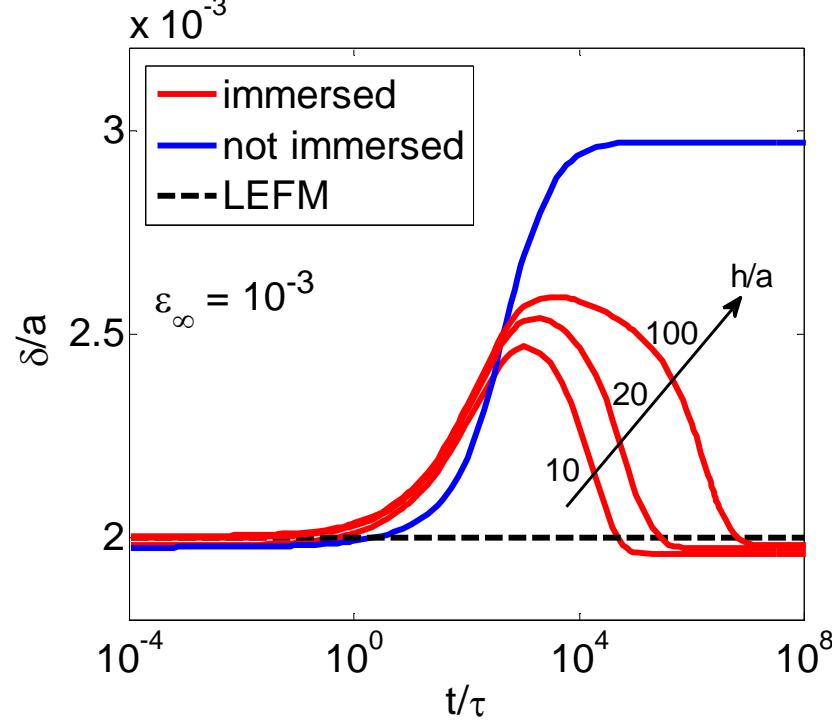
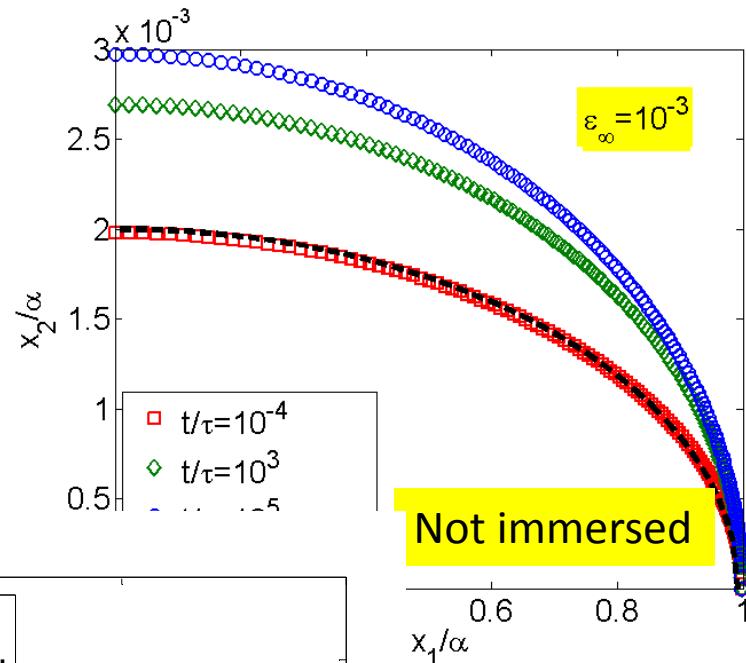
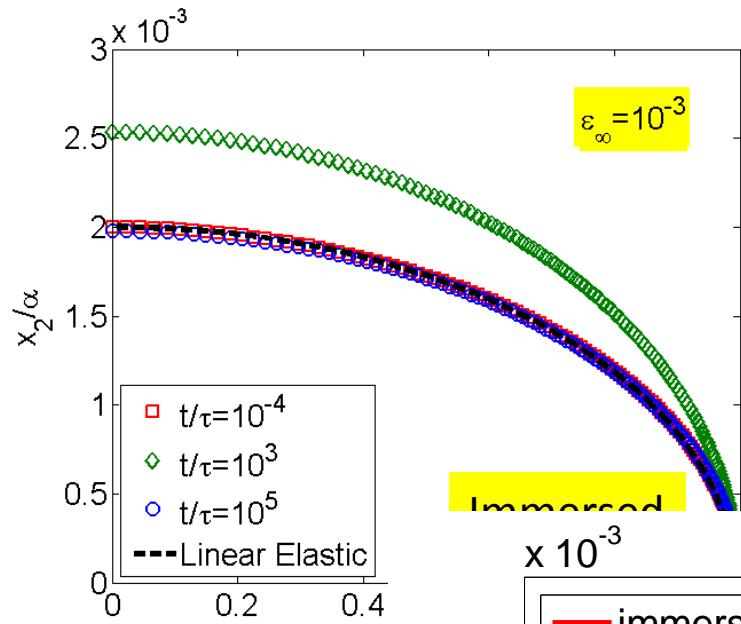
$$t \rightarrow 0 \\ \nu = 0.5$$



$$t \rightarrow \infty \\ \nu = 0.2415$$

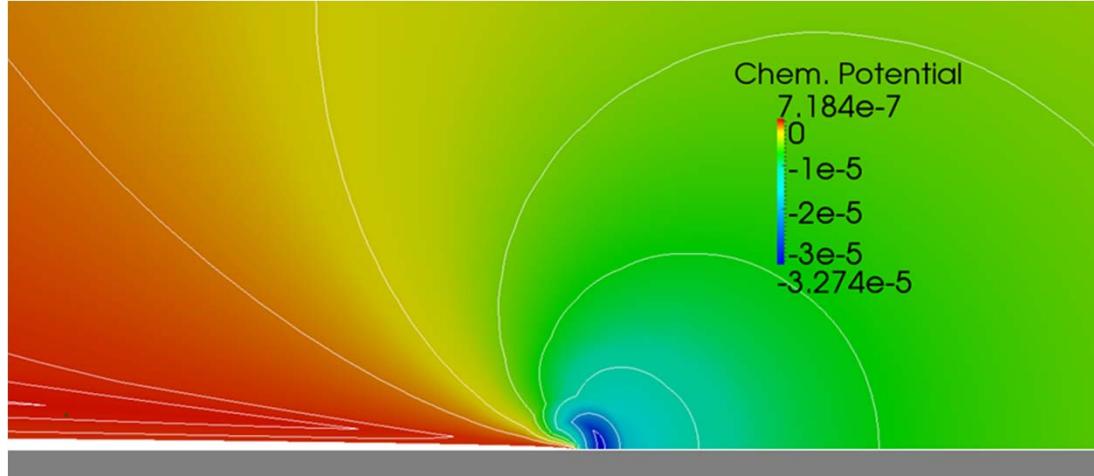
- The square-root singularity is maintained at both the instantaneous and equilibrium states, but the stress intensity factor is lower in the equilibrium state due to poroelastic relaxation.

# Evolution of crack opening

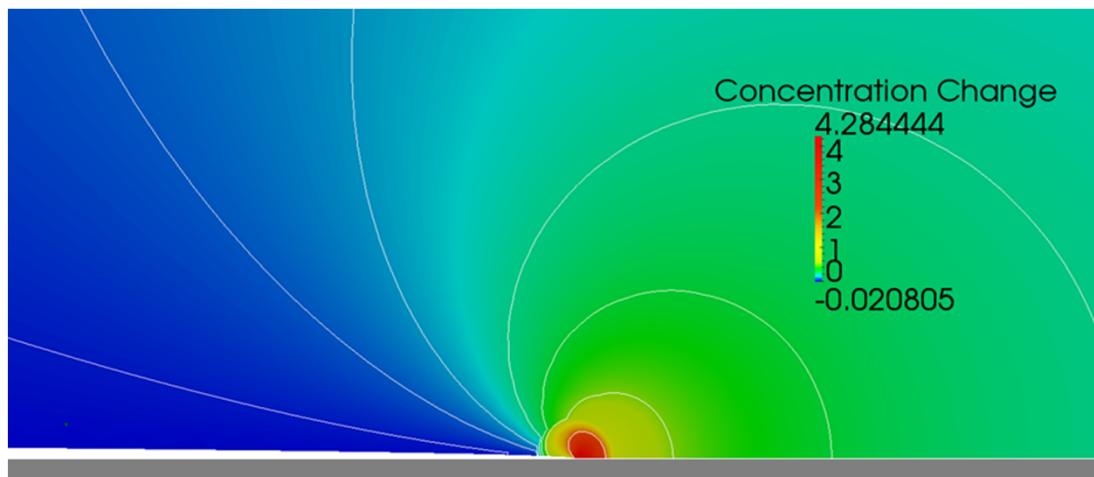


Opening at  
the center:

# Solvent diffusion around crack tip



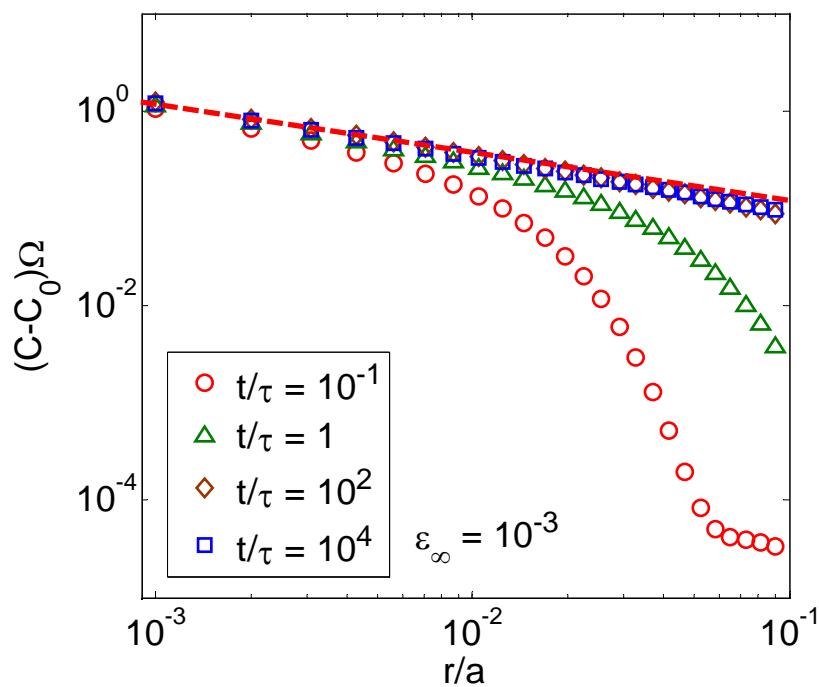
**Instantaneous limit:**  
Homogeneous solvent concentration, but *inhomogeneous* chemical potential.



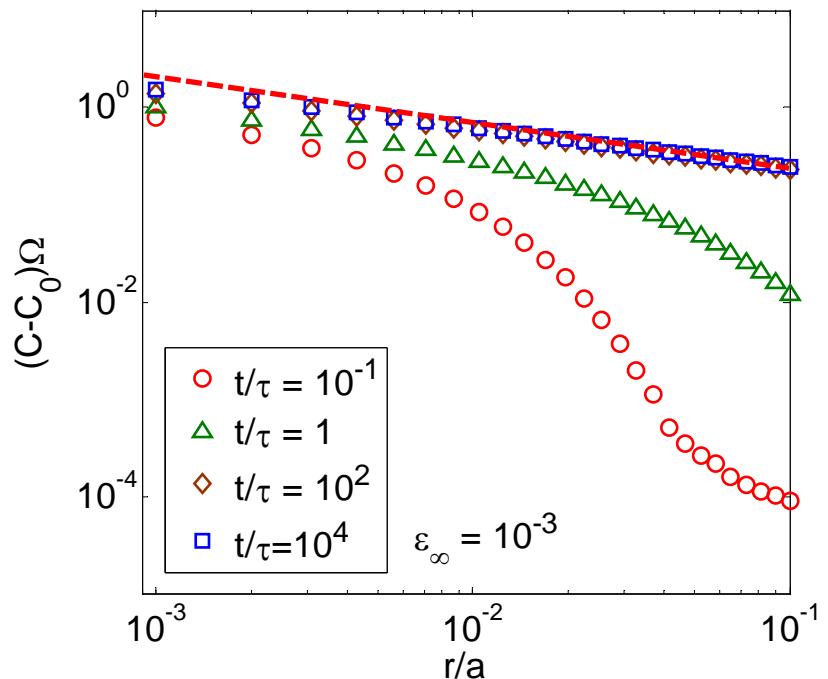
**Equilibrium state:**  
Homogeneous chemical potential, but *inhomogeneous* solvent concentration.

# Evolution of Solvent Concentration

- Immersed



- Not-immersed



A singular concentration field is approached in the equilibrium state for both the immersed and not-immersed cases.

# Energy release rate

- Rate of change of potential energy:

$$\frac{d\Pi}{dt} = \int_{V_0} \frac{dU}{dt} dV - \int_{V_0} b_i \frac{dx_i}{dt} dV - \int_{S_0} T_i \frac{dx_i}{dt} dS - \int_{V_0} \mu r dV - \int_{S_0} \mu i dS$$

- Rate of dissipation due to diffusion:

$$\frac{d\Sigma}{dt} = - \int_{V_0} J_K \frac{\partial \mu}{\partial X_K} dV$$

- Total energy:

$$\Psi = \Pi + \Sigma \quad \frac{d\Psi}{dt} = 0$$

Conserved throughout  
the transient evolution  
(without crack growth).

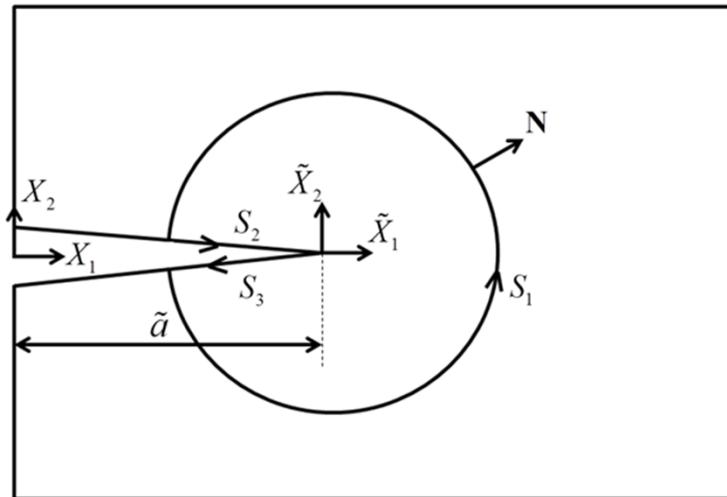
- Rate of total energy change due to crack extension

$$\frac{d\Psi}{d\tilde{a}} = \int_{V_0} \left( \frac{dU}{d\tilde{a}} - \frac{\partial \mu}{\partial X_K} \frac{dI_K}{d\tilde{a}} \right) dV - \int_{S_0} \left( T_i \frac{dx_i}{d\tilde{a}} - \mu N_K \frac{dI_K}{d\tilde{a}} \right) dS$$

# A modified J-integral

Define a nominal energy release rate:  
(per unit length of crack in the  
reference state)

$$J^* = -\frac{d\Psi}{d\tilde{a}}$$

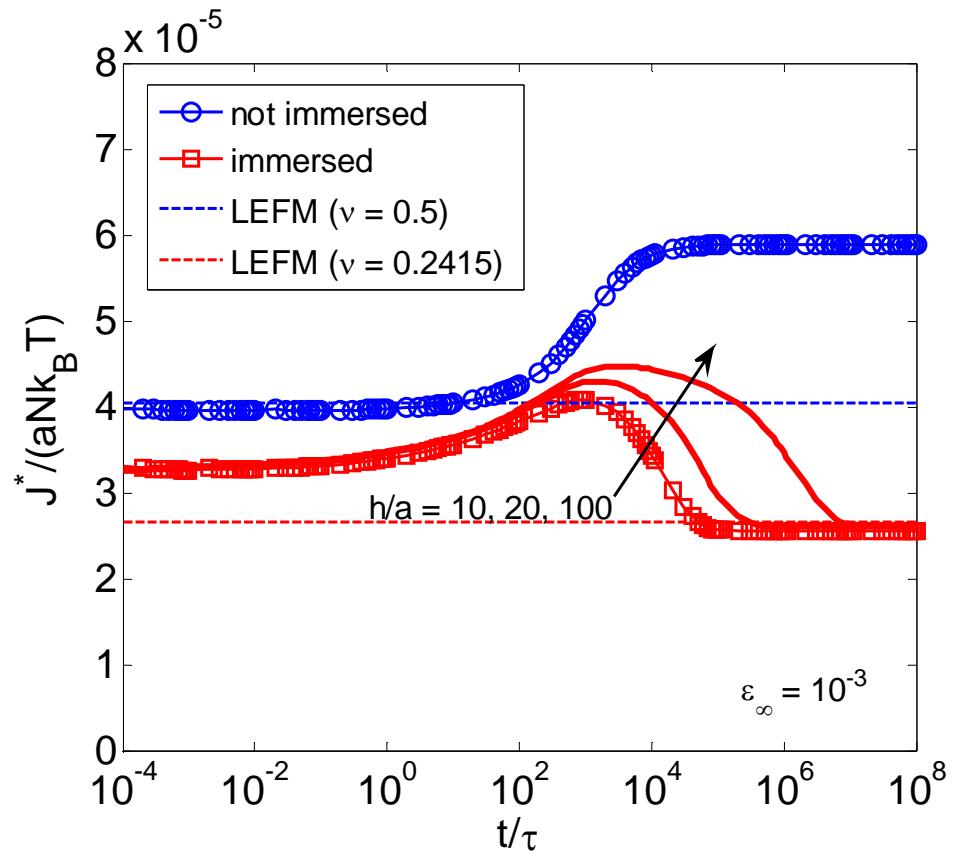
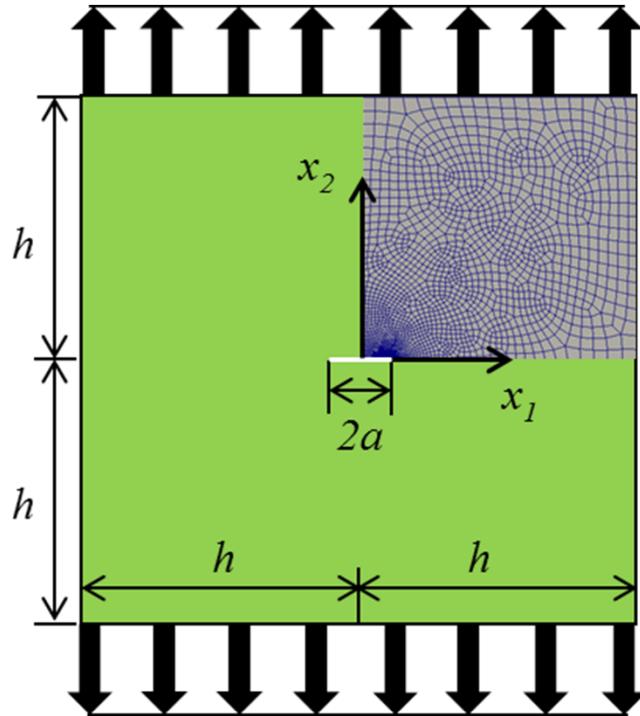


$$J^* = \int_{S_1} \left( UN_1 - s_{iJ} N_J \frac{\partial x_i}{\partial X_1} \right) dS - \int_{V_0} \mu \frac{\partial C}{\partial X_1} dV$$

$$J^* = \int_{S_1} \left( \hat{U}N_1 - s_{iJ} N_J \frac{\partial x_i}{\partial X_1} \right) dS + \int_{V_0} \frac{\partial \mu}{\partial X_1} CdV$$

- $J^*$  is path independent.
- The second form is more convenient for numerical calculations.
- A domain integral method is used to calculate  $J^*$ .

# Evolution of J-integral

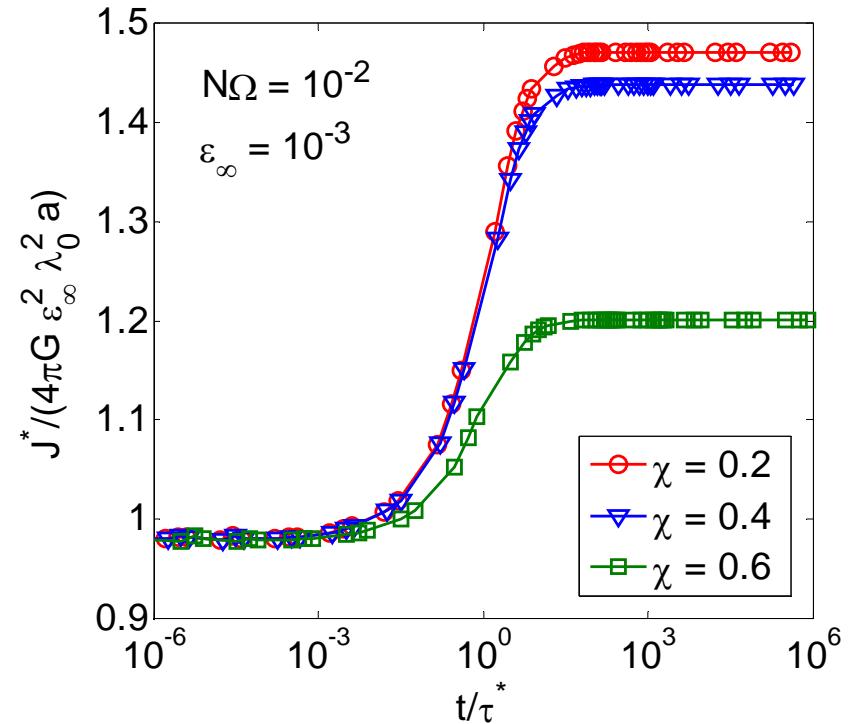
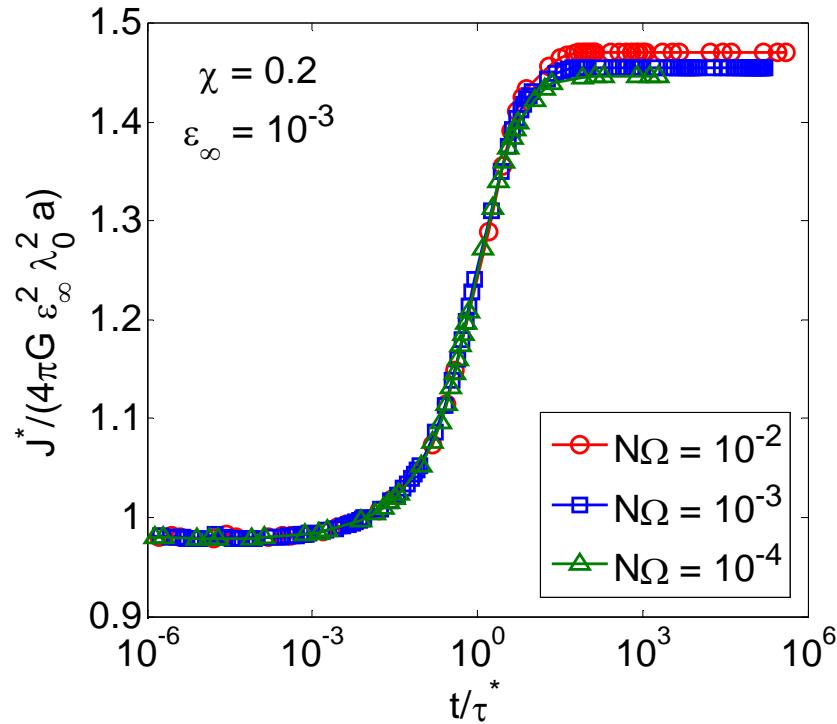


LEFM predictions at the instantaneous and equilibrium limits:

$$J^*(t \rightarrow 0) = 4\pi\lambda_0 N k_B T \varepsilon_\infty^2 a$$

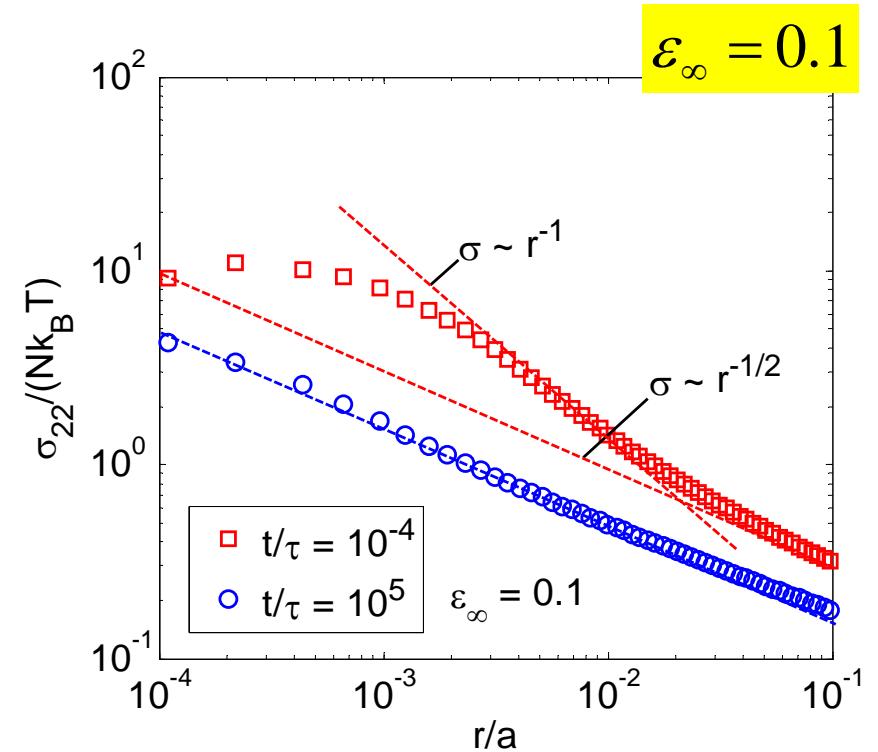
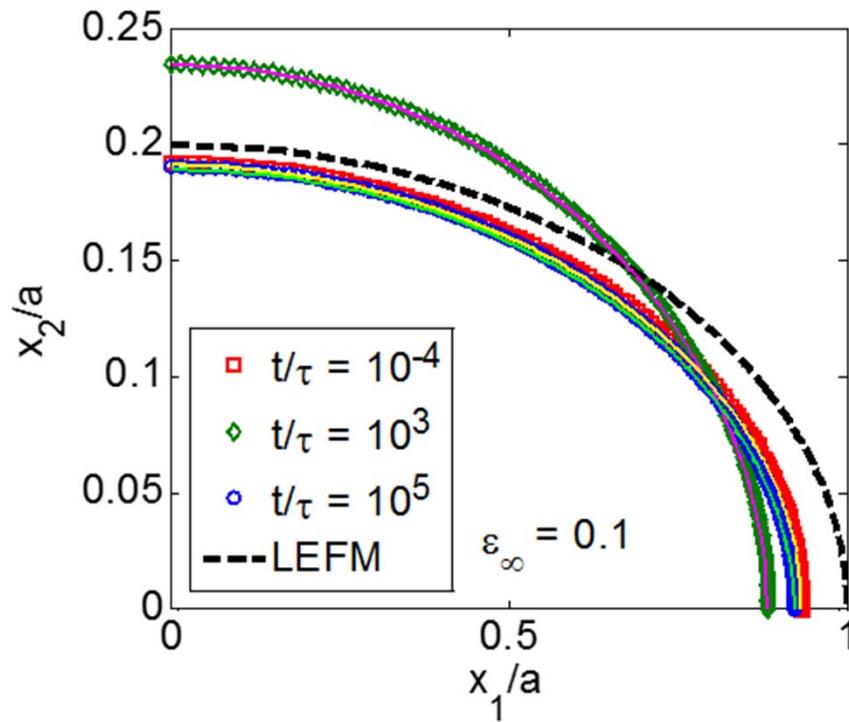
$$J^*(t \rightarrow \infty) = \frac{2\pi\lambda_0}{1-\nu_\infty} N k_B T \varepsilon_\infty^2 a$$

# Dependence on material parameters



- The  $J^*$  is well predicted by LEFM at the instantaneous limit ( $t \rightarrow 0$ )
- The equilibrium  $J^*$  depends sensitively on  $\chi$  (good/poor solvent)
- The time scale is captured effectively by the poroelastic diffusivity
- Delayed fracture possible.

# Under moderately large remote strain

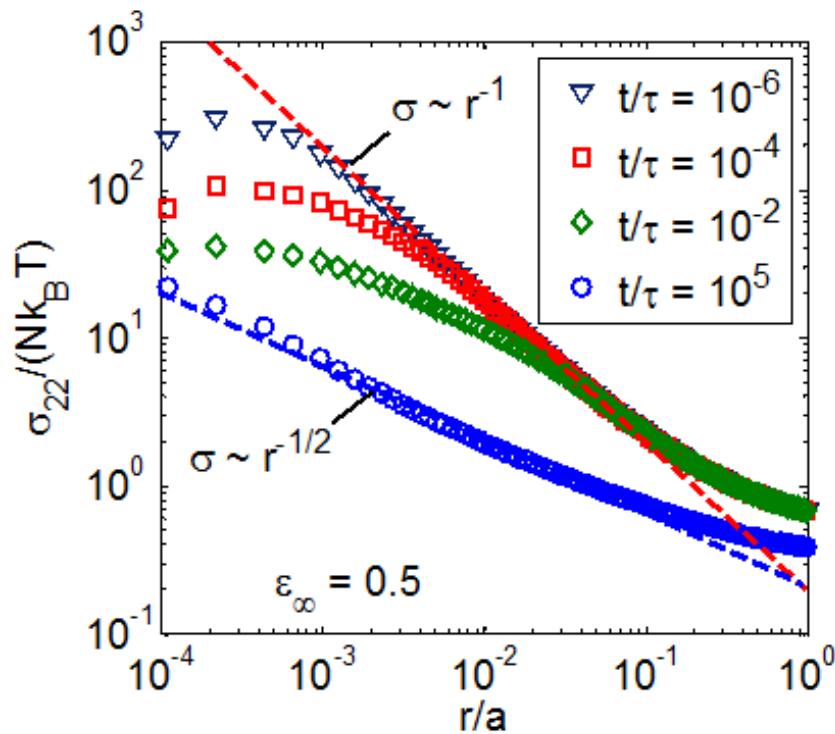


- Similar behavior for crack opening (and  $J^*$  too, not shown)
- Stress distributions show transition of singularity: with a stronger  $1/r$  singularity due to hyperelasticity and a weaker singularity closer to the crack tip due to solvent diffusion; the typical square-root singularity is approached at the equilibrium limit.

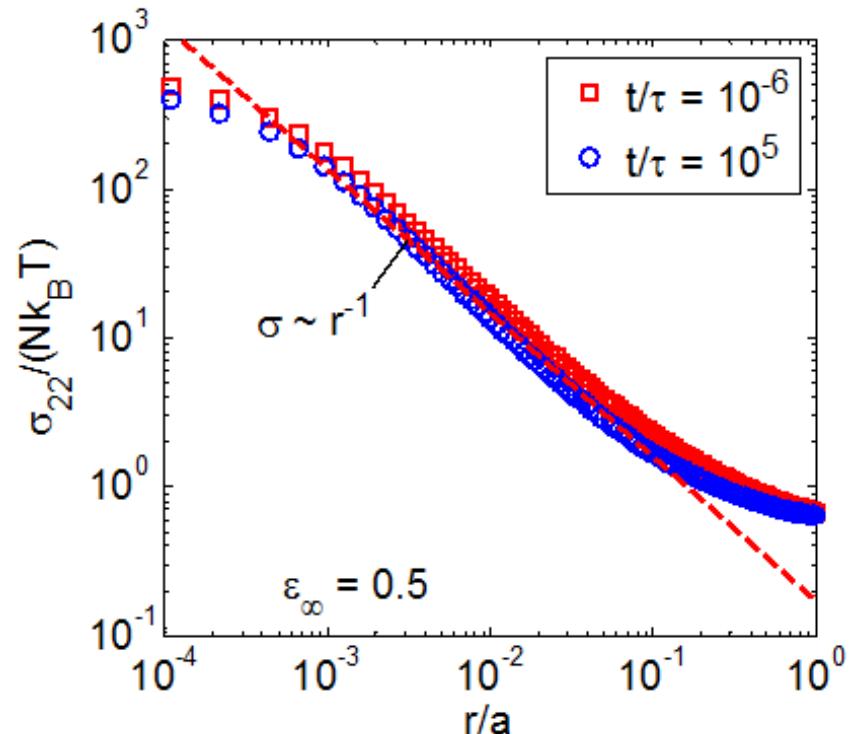
# Under large remote strain

$$\varepsilon_\infty = 0.5$$

Immersed

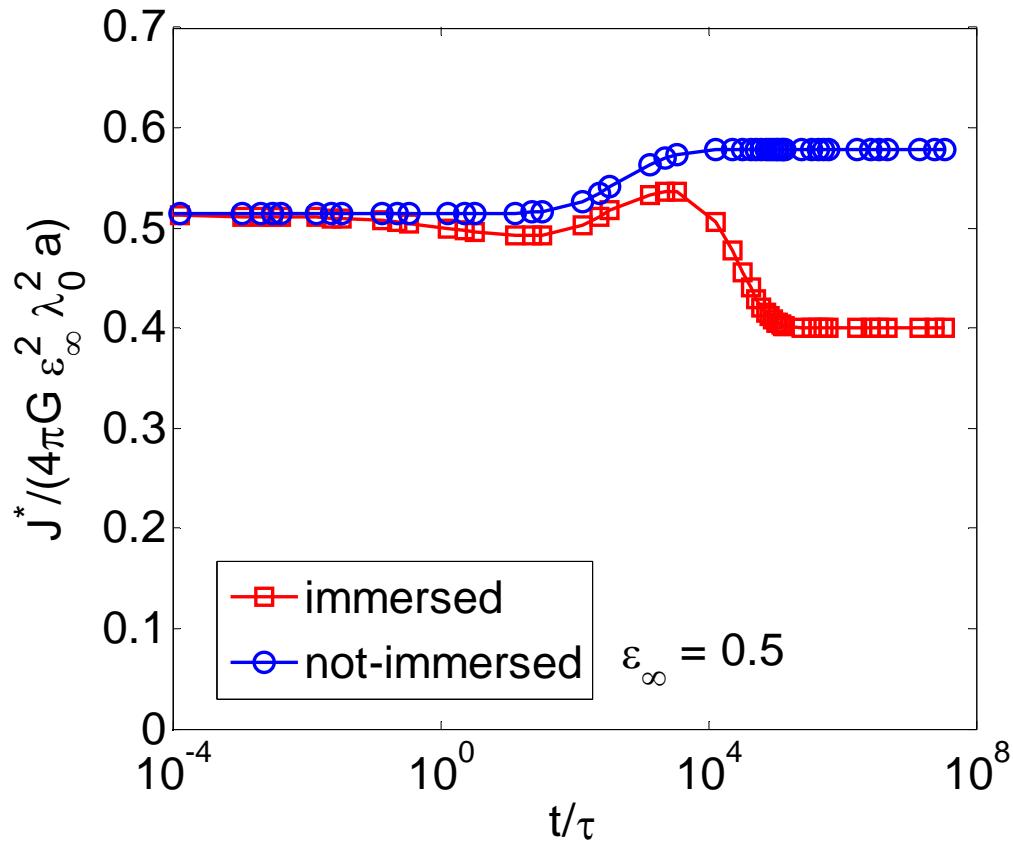


Not-immersed



- The  $1/r$  singularity becomes more prominent in both cases
- The singularity weakens over time for the immersed case

# J-integral



- The  $J^*$  is considerably lower than the LEFM prediction, while the evolution trends are similar to the small-strain behaviors.

# Fracture Criterion

$$J^*(t) = J_c^*(?)$$

- The right hand side of the fracture criterion has to be determined by well-designed experiments.
- Could the right-hand side depend on time due to the evolving, inhomogeneous field of solvent concentration around the crack tip?

# Summary

- A nonlinear, transient finite element method was implemented for large deformation of hydrogels coupled with solvent diffusion.
- The transient processes of constrained swelling (with surface instability) and flat punch indentation were studied in some details.
- Effects of solvent diffusion on the crack-tip fields and driving force for fracture of hydrogels were studied. A path-independent, modified J-integral was derived as the transient energy release rate of crack growth in hydrogels, although a complete fracture criterion is yet to be established.

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