



The University of Texas at Austin  
**Aerospace Engineering  
and Engineering Mechanics**  
*Cockrell School of Engineering*

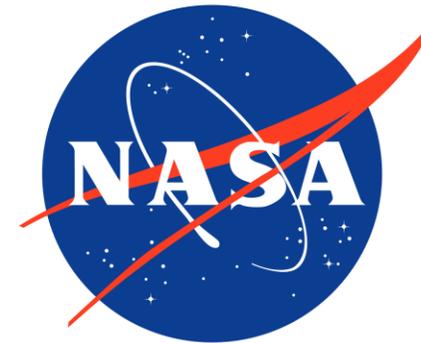
# **TEXAS SPACECRAFT LABORATORY**

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Information Session

# What is TSL?

- Undergraduate-driven laboratory led by Dr. Brandon Jones
- Laboratory focusing on the design, manufacturing, and operation of small satellites
- Focusing on primarily government-funded projects for spacecraft, payload, and algorithm design and implementation



# Projects

## Past Missions

Bevo-1

FASTRAC

RACE

Bevo-2

ARMADILLO

Seeker Vision

## Ongoing Missions

SCOPE-1

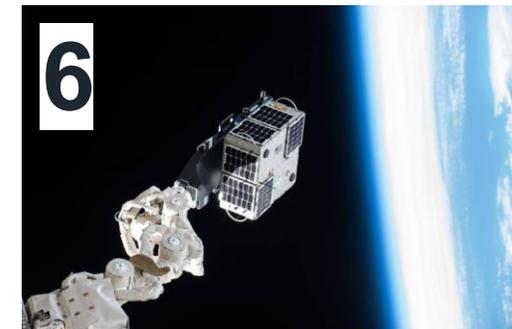
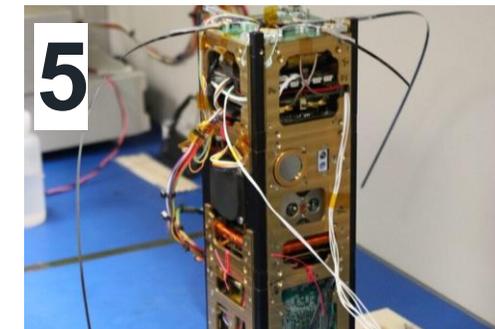
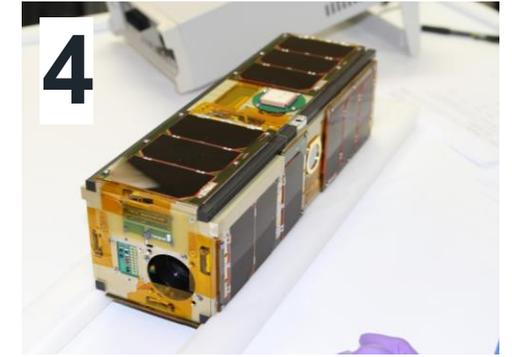
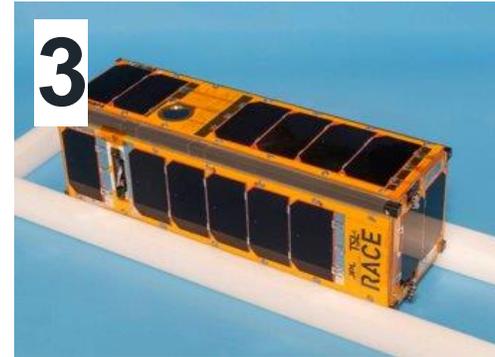
REACT

Weather Balloon

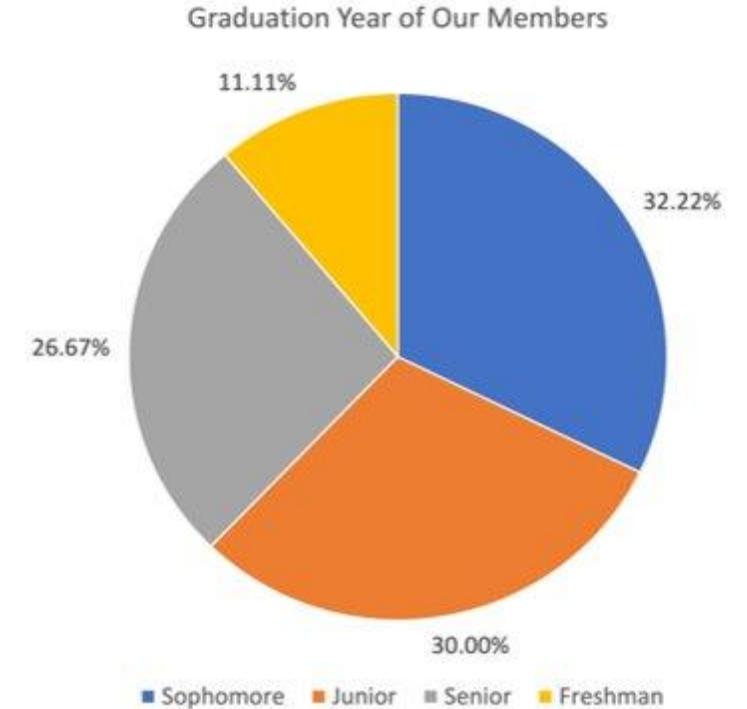
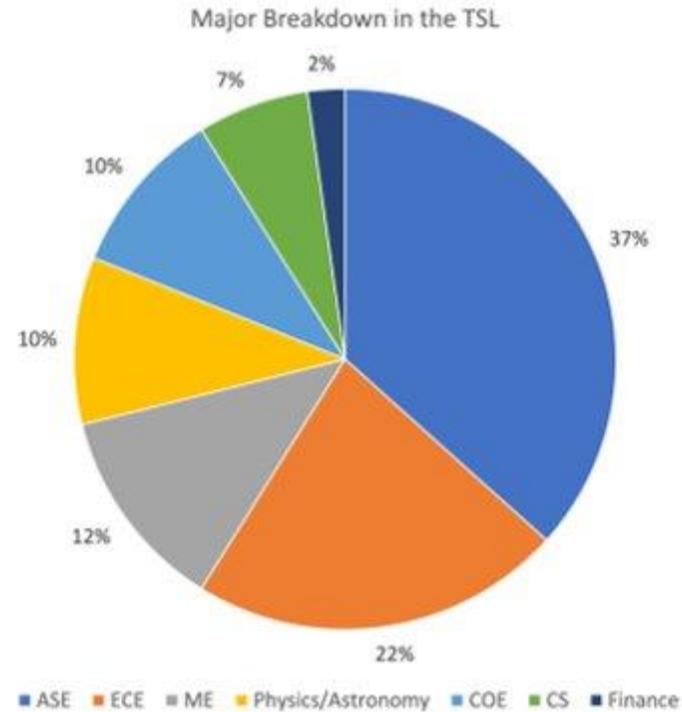
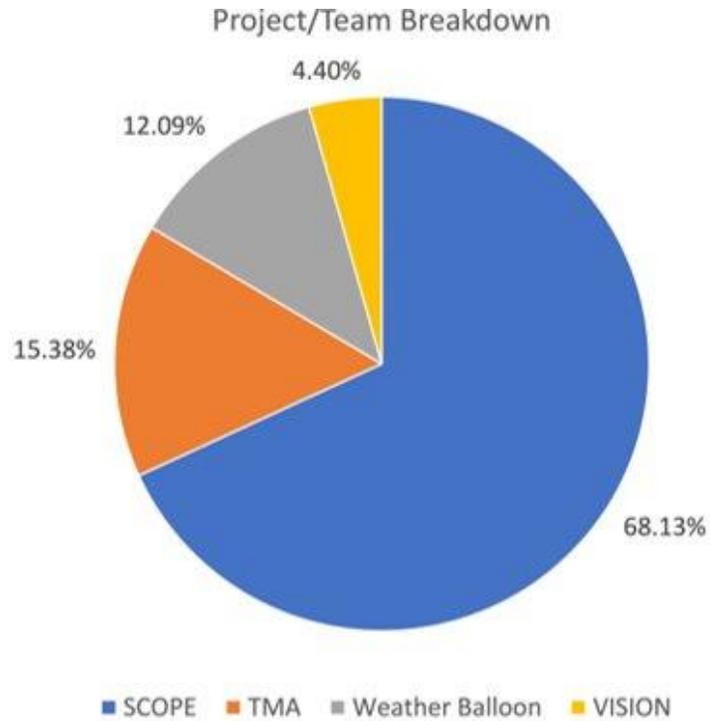


# Past Missions

- 1. Bevo 1 (2009)**
  - Autonomous docking & rendezvous experiment
  - Texas A&M, NASA JSC
- 2. FASTRAC (2010)**
  - Formation Autonomy Spacecraft with Thrust, Relnav, Attitude and Crosslink (FASTRAC)
  - AFRL (UNP-3)
- 3. RACE (2014)**
  - Radiometer Atmospheric CubeSat Experiment (RACE)
  - NASA JPL
- 4. Bevo 2 (2016)**
  - Autonomous docking & rendezvous experiment
  - Texas A&M, NASA JSC
- 5. ARMADILLO (2019)**
  - Atmospheric Related Measurements of Sub-Millimeter Debris in Low Earth Orbit
  - AFRL (UNP-7)
- 6. VISION (Algorithm onboard JSC's SEEKER in 2019)**
  - Visual Identification System for Intelligent Orbital Navigation

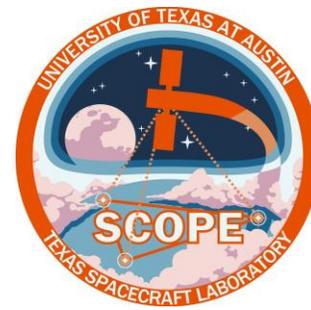


# Typical TSL demographics breakdown



# Ongoing Missions





# SCOPE-1

## Spacecraft for Optical-based Position Estimation-1





# Mission Overview

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Collaboration b/w TSL, UT Grad students, Dr. Jones & Dr. Zanetti

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Sponsored by NASA Small Spacecraft Technology Program

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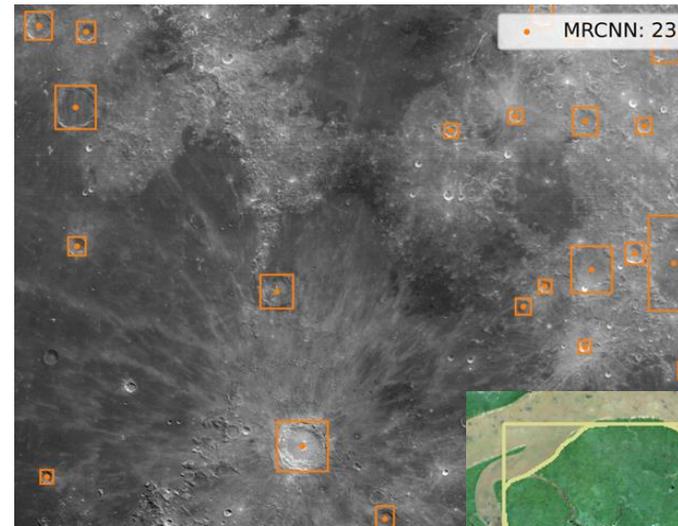
Mature PNT (Position, Navigation, Timing) algorithms originally developed for lunar applications

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Develop new detector for Earth Islands & archipelagos

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Low Earth orbit demo for future lunar application





# Mission Concept

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Capture image of ground target  
(islands/archipelagos)

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Utilizing ML (computer vision) approach,  
estimate spacecraft position and timing on orbit

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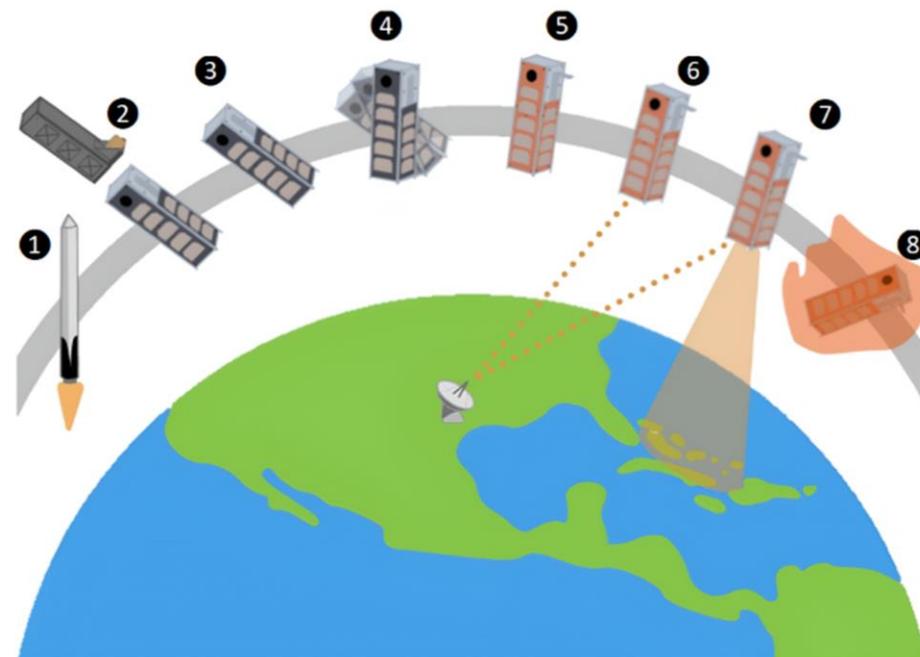
Simultaneously collect position & timing  
information from GNSS

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Post downlink, compare measurements and  
estimates to verify algorithms

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Mission success: 100 m error/axis, 100 ms error





# Mission History

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Started in Fall 2020

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Completion through PDR at the end of Spring 2022

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1 year hiatus until we received approval for funding in Fall 2023

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Completed CDR, currently building flat sat and preparing for SIR

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#### **Mission Requirements Review (MRR)**

*Mission Proposal supported with technology gap assessment, 3+ mission options explored, timeline, overview, risk planning & mitigation, and preliminary design requirements*

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#### **Internal Design Reviews (IDR)**

*Subsystem infrastructure establishment, subsystem requirements, added details to timeline, hardware Design To specifications, and build start of robust documentation*

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#### **Preliminary Design Review (PDR)**

*Establish specifications, drawings, ICD's, qualification plans, optimize schedule and cost decisions, and resolve any system requirement conflicts*

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#### **Critical Design Review (CDR)**

*Subsystem design details meeting all subsystem requirements, hardware Build to specifications, operations plan and robust documentation within design deliverables*

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#### **Test Readiness Review (TRR)**

*Complete set of procedures, software test configuration, quality control plans, post-test data handling plans, and acceptance criteria*

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#### **Flight Readiness Review (FRR)**

*Trained personnel, operational readiness criteria, verification requirements compliance, verification procedures and data, launch facility checkout, and go/no go criteria*





# SCOPE-1

# Subteams

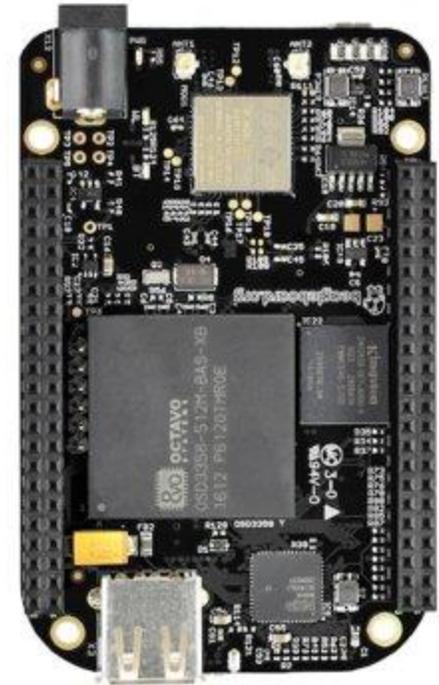




# Command and Data Handling (CDH)

What we do

- Develop software in Fprime to control other components on the satellite bus, route and store data products (telemetry, results, event logs etc.)
  - Utilizing BeagleBoneBlack as Flight computer





# Communications (COM)

What we do:

- Procure and test communications hardware including satellite radios and antennas
- Develop Link budgets and communications data requirements
  - Involves FCC RF and NOAA Imaging Licensing
- Create software to manage messages sent to and from the satellite
- Operate the Lab ground station located on the ASE garage rooftop





# Electrical and Power Systems (EPS)

## What We Do:

- Select and test electrical power hardware, including batteries, solar panels, and ground test equipment
- Develop system Power Budget and run energy analysis simulations to predict power consumption in orbit
- Support other subsystems with PCB development, especially with power electronics and converters

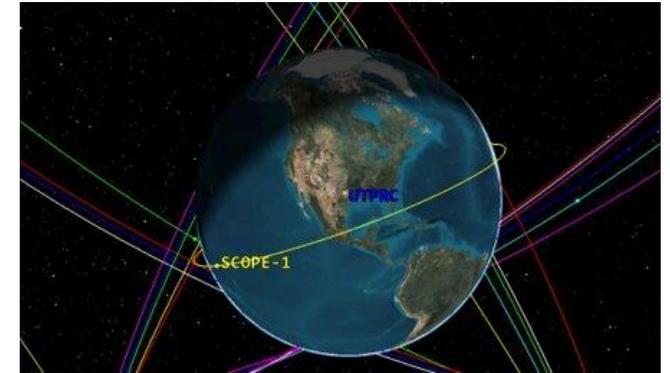




# Flight Dynamics Systems (FDS)

## What We Do:

- Identify, simulate, and interface with attitude determination and control hardware (reaction wheels, magnetorquers).
- Work with GPS/GNSS receiver calibration and work on mission design/modeling.
- Generate detumble analysis, pointing budgets, island coverage simulations, etc.

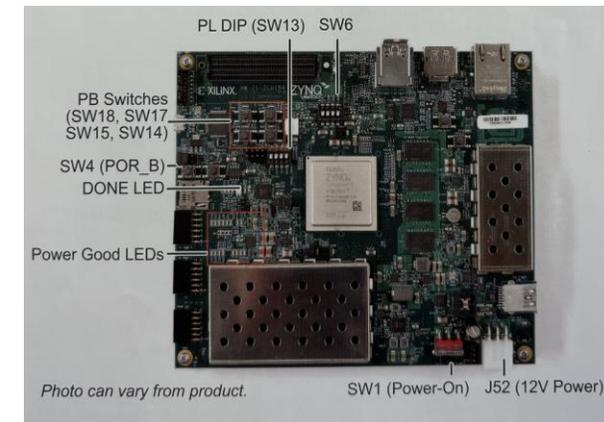




# Payload (PAY)

## What We Do:

- Create and document the payload system and integrate the payload system into the overall satellite structure.
- Develop and train ML/computer vision island detector model
- Develop methods of testing hardware and software components to optimize the payload system.



## Nvidia Jetson Developer Kit

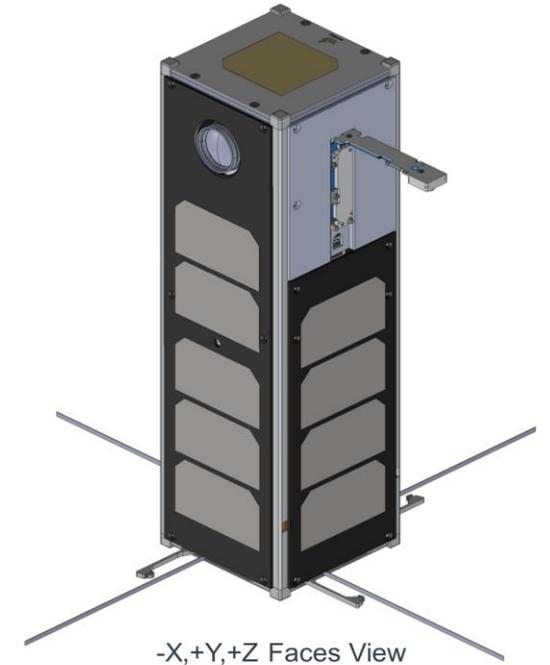




# Structures (STR)

## What We Do:

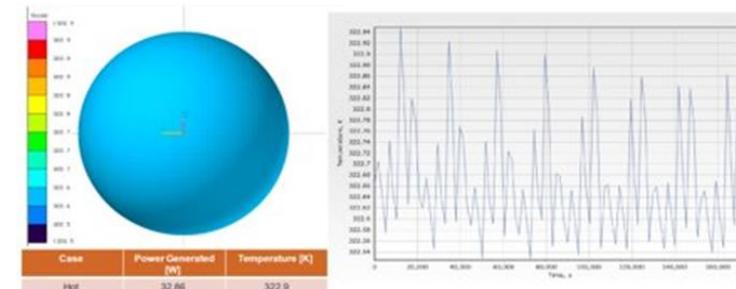
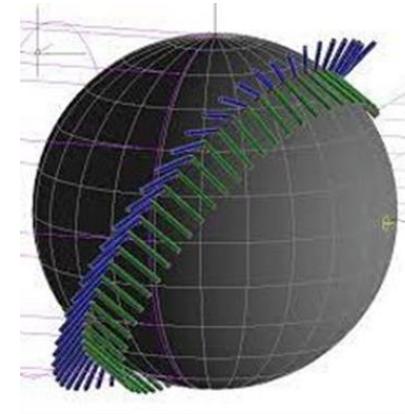
- Obtain, utilize, and integrate CAD assets into high-fidelity assembly
- Design custom component mounting structures
- Finite-element analysis of satellite model, including steady-state and vibrational forces
- Prepare satellite assembly procedure documents and assemble physical satellite



# Thermal Protection Systems (TPS)

## What We Do:

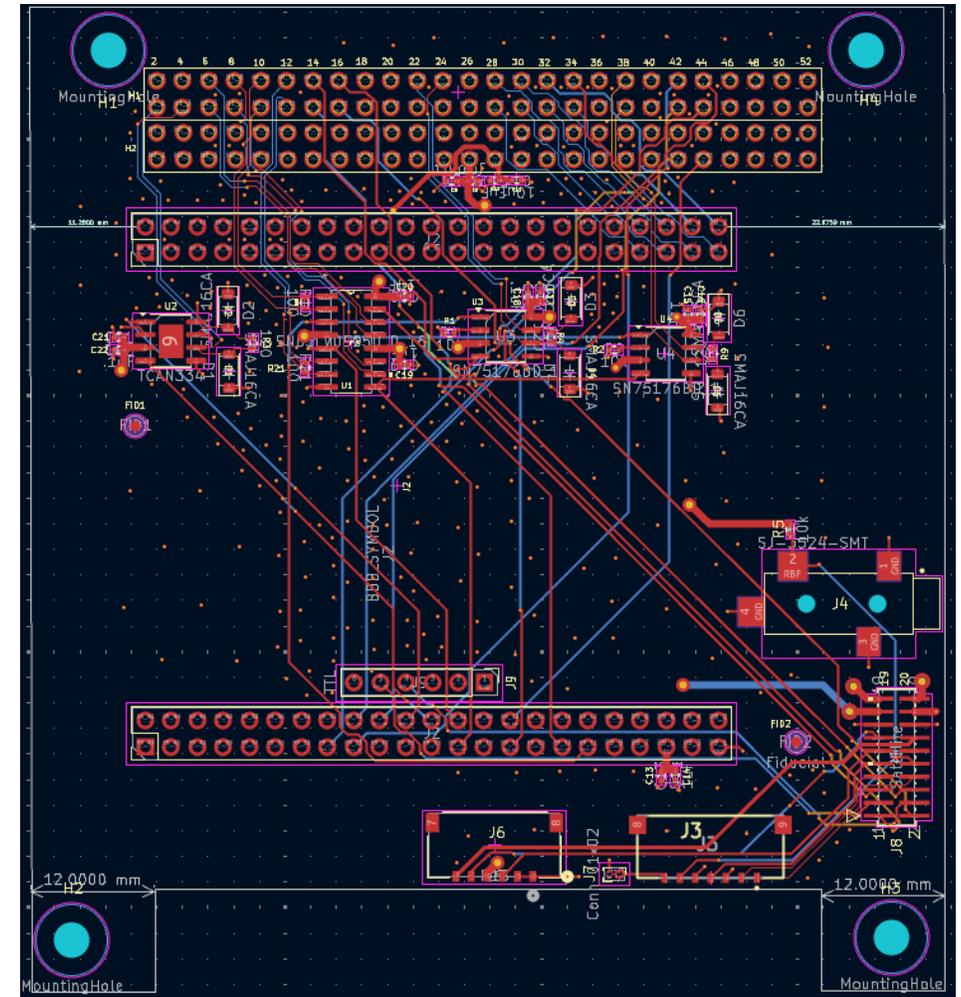
- Analyze and model the thermal profile to ensure all components are in the working in their ideal temperatures
- Develop temperature/thermal budgets



# PCB/SYS Team

## What We Do:

- Design interface boards using KiCad
- Assemble, test and integrate the boards with the rest of the flight hardware & software





# REACT

**Reaction-wheel Emissions and  
Analysis Control Team**



# REACT OVERVIEW

## Focus:

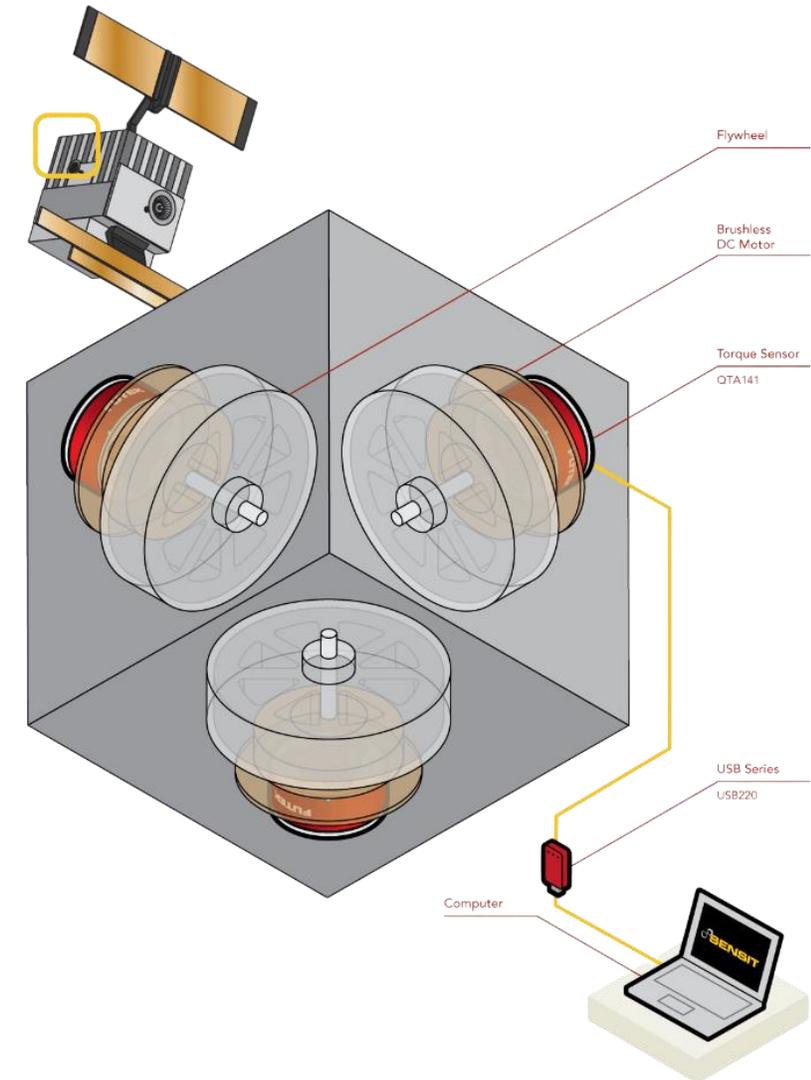
Investigating magnetic field emissions from satellite reaction wheels

## Why it matters:

Emissions can interfere with sensitive instruments and degrade satellite performance

## Goal:

Develop and test mitigation strategies that improve satellite reliability



# Mission Timeline

## Phase 1:

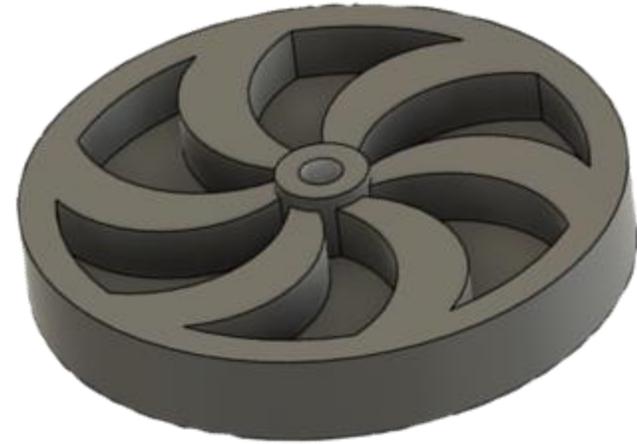
Build and test our own reaction-wheel, proving the problem exists

## Phase 2:

Research and prototype mitigation techniques

## Phase 3:

Analyze data and publish results to push the field forward.



# Team Structure

## Hardware

- CAD design
- Machining
- Test stand builds
- Reaction wheel fabrication

## Electronics

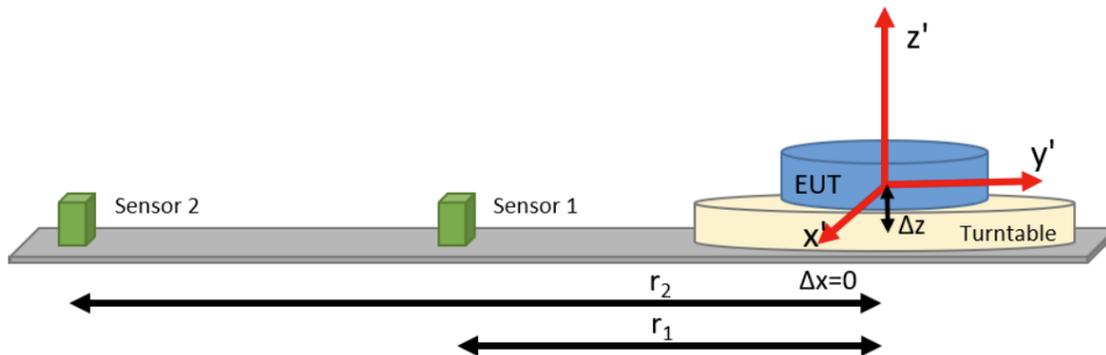
- Sensors
- Wiring
- PCBs
- Signal Processing
- EMI testing.

## Software

- Data collection
- Automation
- Modeling
- Control algorithms.

## Physics

- Magnetic field modeling
- Data interpretation
- Paper writing
- Experimental Analysis





# Weather Balloon

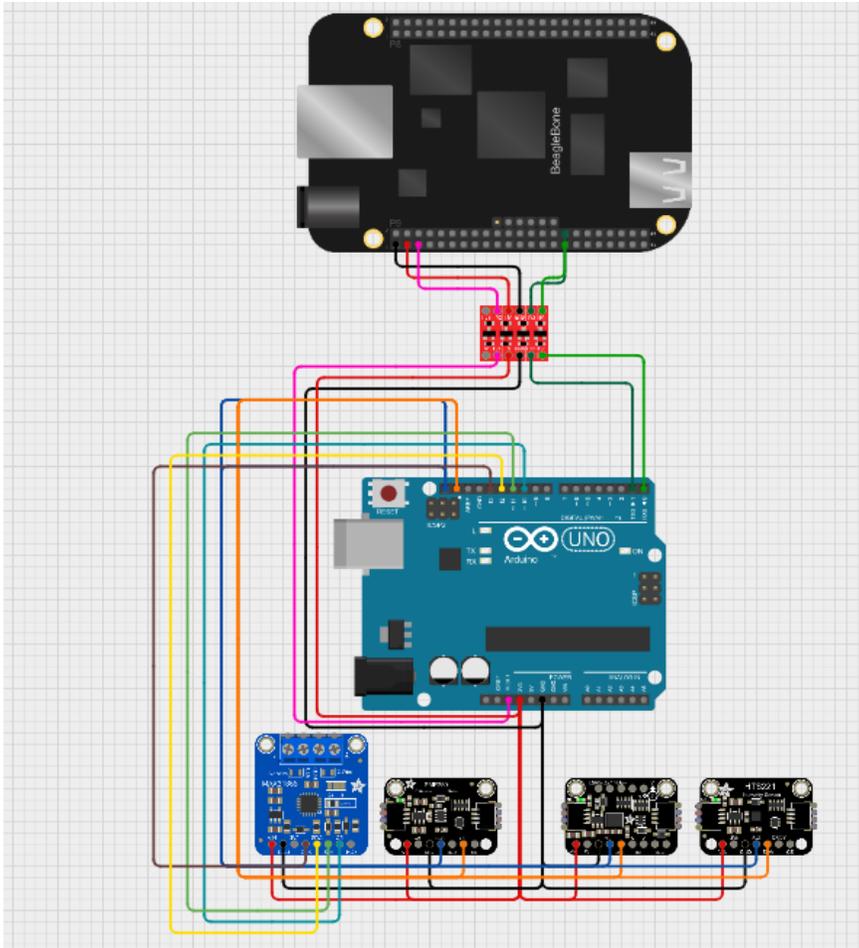


# What We Do

## Objectives:

- Designing a high altitude balloon testbed to be used as a risk testing platform by other TSL missions
- Create a testbed apparatus that is compatible with other mission's equipment to allow for testing at near space altitudes
- Payload will act as its own CubeSAT that is trackable and recoverable
- Provide an onboarding experience reflective of satellite design process





```
Serial.begin(9600);  
while (!Serial) delay(10); // wait for the Serial Monitor  
  
// Initialize the sensor  
if (!lsm.begin()) {  
  Serial.println("Failed to find LSM9DS1 chip");  
  while (1) delay(10);  
}  
  
// Set ranges for accelerometer, gyroscope, and magnetometer  
lsm.setupAccel(lsm.LSM9DS1_ACCEL_RANGE_2G);  
lsm.setupGyro(lsm.LSM9DS1_GYRO_SCALE_245DPS);  
lsm.setupMag(lsm.LSM9DS1_MAG_GAIN_4GAUSS);  
  
Serial.println("LSM9DS1 Found!");
```



# Project Phases

## Low Altitude Balloon Test

- Purpose: Test basic payload design and integration and establish launch procedures
- Progress: Assembly

## High Altitude Balloon Test

- Purpose: Test more advanced payload at higher altitudes and establish launch, tracking, and recovery procedures
- Progress: Assembly

## High Altitude Balloon Testbed

- Purpose: Create a high altitude testing platform for TSL missions and TMA projects
- Progress: Concept of Operations



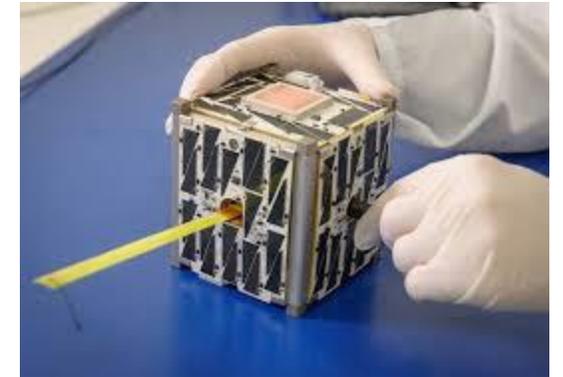


# Other Projects/Teams



# Freshman Exploratory Team

- On-ramp for freshmen to work on SCOPE-1 and REACT
- One-semester project where you learn the NASA systems engineering process on a well-defined project
  - Start from PI/Lab provided Needs, Goals, and Objectives to produce a working implementation
  - Work with existing TSL leaders and learn about our ongoing projects
  - Learn about small satellite development, ESD/Clean room protocol, and more
- Upon completion of the project, “graduate” to an existing TSL project





# Spring 2026 Exploratory Project

- **Purpose:** Provide a structured onboarding resource so new TSL members can quickly learn lab organization and systems engineering practices
- **Goal:** Create an extensible and easily managed resource that trains new members of the TSL on lab processes, subsystem documentation, and project fundamentals
- **Scope:** Focus on systems engineering, design, and implementing training modules; content guidance provided by leadership
- **Deadline:** Before start of Spring 2026 semester



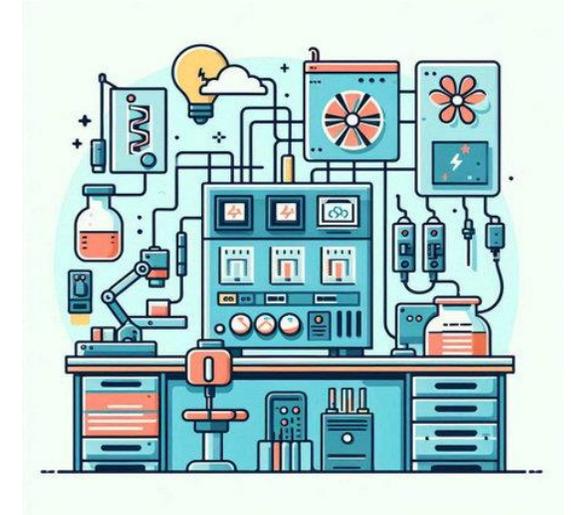
# Lab Operations

## Logistics

- Social media management, internal comms, event organization

## Facilities

- Oversee day-to-day operations, manage documentation, streamline equipment usage
- Thermal chamber, vacuum chamber, satdex, and purchasing POCs



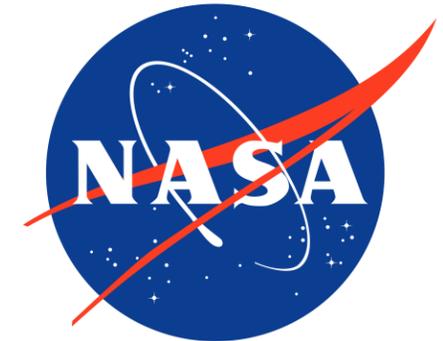


# Application Info



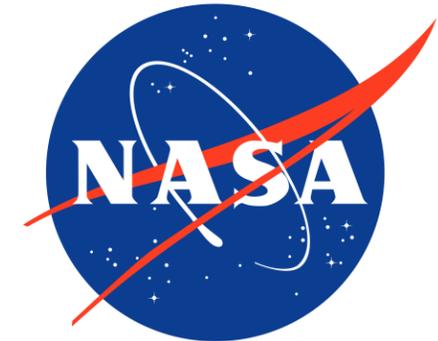
# TSL Recruitment Information

- Application opens **Tuesday, January 20th.**
- If you apply **BEFORE Monday, January 25th**, we will aim to email you a decision no later than **Monday, February 8th.**
- If you apply **AFTER Monday, January 25th**, decisions will be made on an as-needed/rolling basis (you may not get a response).
- Must have a GPA of at least 3.0.
- All applicants must be a U.S. citizen or U.S. permanent resident.
  - If you'll be attending UT for at least one more year (through Spring 2027), then you may be eligible as well.
  - Come talk to us afterwards!



# TSL Recruitment Advice

- All applicants must complete the Authorization and Release of Private Information form; applications will not be considered without it.
- Fill in **all** questions on the application.
  - Even if you are applying during the "rolling"/non-response-guaranteed phase.
  - We do not consider incomplete applications.
- Be prepared to talk in depth about any technical experience or projects on your resume.
- Your essays should aim to highlight all your technical experiences.
  - In the application backend, it is much easier for us to access and read your essays than your resumes.
- Upload any documents, projects, research, etc. you want to show off.
- If you apply earlier, your application will be looked at and decided on sooner.



# Join Us!

TSL Email List:

<https://bit.ly/3AYN08U>



Follow the Instagram for  
application updates!

@ut.tsl



# Attendance and Application Forms



## Application Form

[https://utexas.qualtrics.com/jfe/form/SV\\_6P0Z06uAOB80AoC](https://utexas.qualtrics.com/jfe/form/SV_6P0Z06uAOB80AoC)



## Attendance Form

[https://utexas.qualtrics.com/jfe/form/SV\\_1XG8pFFEPAIx9ki](https://utexas.qualtrics.com/jfe/form/SV_1XG8pFFEPAIx9ki)





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# Questions?

Stick around or email [tsl.director@utexas.edu](mailto:tsl.director@utexas.edu)!



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